



ND-500 Single Prec.  
Array Proc. Func.  
ND-805013.3 EN





*ND-500 Single Prec.  
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ND-805013.3 EN*

*NOTE:*

*The numbering system for Norsk Data's documentation changed in September 1988. All numbers now start with an 8. The numbering structure is therefore ND-8xxxx.xx xx. Example: ND-863018.3A EN. Existing manuals will receive a new number if and when they are updated or revised.*

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## Preface:

### THE PRODUCT

This manual describes the mathematical functions in the ND-500 APF library.

The APF library routines may be called from FORTRAN. The routines are designed to speed up the execution of operations on single precision real arrays.

The APF library utilizes a special microprogram for the ND-500 CPU. This microprogram is an extension of the standard microprogram.

The ND-numbers for this product on the different ND-500 models are:

Computer	ND-number	Microprogram version
ND-500/1 series	ND-10338	104xx
----- " -----	ND-10412	106xx
ND-500/2 series	ND-10701	152xx
----- " -----	ND-10786	152xx
ND-570/2 serie	ND-10700	150xx

NOTE The ND-530/2 can not use this product.

### THE MANUAL

This manual provides a functional description of the APF library, and thereby the special array processing functions. A listing of each routine is used to describe the routines. Listing and parameter description is mainly in FORTRAN. Two of the routines are described in ND-500 assembler, although they are callable from FORTRAN.

### CHANGES FROM PREVIOUS VERSION

The description of the routines is revisited to make this manual consistent with the related manual ND-500/2 Double Precision Array Processing Functions, ND-05.018. Small changes is done in the structure. Some documentation errors are corrected.

### THE READER

This manual is written for people creating and running programs using array processing functions.

PREREQUISITE KNOWLEDGE

The reader is assumed to be familiar with FORTRAN and ought to have some knowledge of the ND-500 assembler. It is also assumed that the reader is familiar with using ND-500 computers, and knows how to generate, load and run programs on such systems.

RELATED MANUALS

Documentation further describing the use of ND-500 computers is found in these manuals:

ND-500 Loader/Monitor	ND.60.136
ND FORTRAN Reference Manual	ND.60.145
ND-500 Reference manual	ND.05.009
ND-500/2 Double Precision Array Processing Functions	ND.05.018

## TABLE OF CONTENTS

Section	Page
1 BASIC CONCEPTS . . . . .	1
1.1 Prerequisite Software for Using the APF Library . . . . .	1
1.2 The Single Precision Floating Point Format . . . . .	1
1.3 Hardware Concepts . . . . .	1
1.4 Array Processing Definitions . . . . .	2
 2 USING THE ARRAY PROCESSING FUNCTIONS . . . . .	 5
 3 ND-500 ARRAY PROCESSING FUNCTIONS PERFORMANCE . . . . .	 11
3.1 ND-560/1 Processing Performance . . . . .	11
3.2 ND-570/2 Processing Performance . . . . .	13
 4 ARRAY PROCESSING FUNCTIONS . . . . .	 15
4.1 Introduction . . . . .	15
4.2 Vector Add (VADDXXX) . . . . .	16
4.3 Vector Subtract (VSUBXXX) . . . . .	17
4.4 Vector Multiply (VMULXXX) . . . . .	18
4.5 Vector Divide (VDIVXXX) . . . . .	19
4.6 Vector Maximum (VMAXXXX) . . . . .	20
4.7 Vector Minimum (VMINXXX) . . . . .	21
4.8 Vector Maximum Magnitude (VMAXMGX) . . . . .	22
4.9 Vector Minimum Magnitude (VMINMGX) . . . . .	23
4.10 Vector Square (VSQXXXX) . . . . .	24
4.11 Vector Signed Square (VSSQXXX) . . . . .	25
4.12 Vector Absolute Value (VABSXXX) . . . . .	26
4.13 Vector Square Root (VSQRTXX) . . . . .	27
4.14 Vector Sine (VSINXXX) . . . . .	28
4.15 Vector Cosine (VCOSXXX) . . . . .	29
4.16 Vector Move (VMOVXXX) . . . . .	30
4.17 Vector Swap (VSWAPXX) . . . . .	31
4.18 Vector Negative (VNEGXXX) . . . . .	32
4.19 ND to IBM Floating Point Convert (NDFPCV) . . . . .	33
4.20 IBM to ND Floating Point Convert (IBMFPCV) . . . . .	35
4.21 Sum of Vector Elements (SVEXXXX) . . . . .	37
4.22 Sum of Vector Elements Magnitude (SVEMGXX) . . . . .	38
4.23 Sum of Vector Elements Square (SVESQXX) . . . . .	39
4.24 Sum of Vector Elements Signed Square (SVSXXXX) . . . . .	40
4.25 Vector Average Absolute Value (VAVGABS) . . . . .	41
4.26 Maximum Value in Vector (MAXVXXX) . . . . .	42
4.27 Minimum Value in Vector (MINVXXX) . . . . .	43

Section	Page	
4.28	Maximum Magnitude Element in Vector (MAXMGVX) . . . . .	44
4.29	Minimum Magnitude Element in Vector (MINMGVX) . . . . .	45
4.30	Maximum and Minimum Value in Vector (MAXMINX) . . . . .	46
4.31	Maximum and Minimum Magnitude Element in Vector (MXMNMGX)	47
4.32	Vector Scalar Add (VSADDXX) . . . . .	48
4.33	Vector Scalar Multiply (VSMULXX) . . . . .	49
4.34	Vector Scalar Divide (VDIVSXX) . . . . .	50
4.35	Dot Product (DOTPRXX) . . . . .	51
4.36	Vector Clear (VCLRXXX) . . . . .	52
4.37	Convolution (CONVXXX) . . . . .	53
4.38	Complex Vector Multiply (CVMULXX) . . . . .	55
4.39	Complex Fast Fourier Transform (CFFTXXX) . . . . .	56
4.40	Real Fast Fourier Transform (RFFTXXX) . . . . .	61
4.41	Vector Taper (VTAPERX) . . . . .	65
4.42	Wiener Filter (WIENERX) . . . . .	66
4.43	Vector Generate (VGENXXX) . . . . .	68
4.44	Vector Linear Interpolation (VNMOXXX) . . . . .	69
4.45	Vector Sinc Interpolation (VNMOXXX) . . . . .	71
4.46	Vector Expand (VXPNDXX) . . . . .	73
4.47	Vector First and Last Non-Zero Value (VFLNZXX) . . . . .	74
4.48	Vector Scalar Multiply and Add (VSMADDX) . . . . .	75
4.49	Predict (PREDICT) . . . . .	76
4.50	Display Processor Function (XBTMUX) . . . . .	77
4.51	Image Build (IMGBLD) . . . . .	78
4.52	Convert and Move (APMOVE) . . . . .	80
4.53	Demultiplex (DMXB) . . . . .	82
5	FAST BYTE MOVE . . . . .	85
Index		87



## 1 BASIC CONCEPTS

### 1.1 PREREQUISITE SOFTWARE FOR USING THE APF LIBRARY

Together with the microprogram, the APF library must be installed. The actual file name is: ND-500-APF-LIB:NRF.

These are the only modifications to be performed on the system.

The APF library utilizes a special microprogram for the ND-500 CPU. This microprogram contains the array processing functions. It is an extension of the standard ND-500 instruction set.

The array processing functions are floating point operations performed in 32 bits floating point format by the ND-500 floating point arithmetic.

### 1.2 THE SINGLE PRECISION FLOATING POINT FORMAT

The number range for the single precision floating point format is:

$$8.6 \times 10^{-78} \leq |N| \leq 5.8 \times 10^{76}$$

The accuracy corresponds approximately to 7 decimal digits.

### 1.3 HARDWARE CONCEPTS

The ND-500 CPU gives the possibility of parallel processing. This means that indexing, memory access, floating point arithmetic, integer arithmetic and loop control may be run in parallel. This is done as far as possible to obtain high speed operations. Temporary results to be used in later calculations, are kept in registers in the ND-500 CPU, accessed directly by both the floating point arithmetic and integer arithmetic.

Arrays involved in an operation are accessed through the ND-500 memory management system. This system will cause automatic allocation of memory, and reservation of continuous memory space for array processing is not required. The result of an array processing function is present in the output array when returning from the function.

The ND-500 array processing functions are fully interruptable to maintain the ND-500 CPU resources being shared by the different processes currently running on the system.

#### 1.4 ARRAY PROCESSING DEFINITIONS

An array contains a group of numbers that are related to each other in some way, and the array may be multi-dimensional. An array is termed a matrix in mathematical terminology.

An array is used to represent equations of different kinds, for example, linear equations. Each row in the array represents one particular equation, thus the array represents a system of equations of the same kind.

The entries in the array are the coefficients of the equations. They are called elements in this manual.

Each row of elements is named a vector in this manual, regardless of what kind of equation it mathematically represents. In those array processing functions which are closely related to mathematical vectors, the row of elements is referred to as a complex vector.

Most of the array processing functions are performed on one-dimensional vectors.

Three parameters are necessary to specify a vector:

V - The logical name of the vector. A single precision real.

INC - The step value (increment) for the index in the array.  
An integer.

NN - Element count. Number of elements in the array. An integer.

NOTE It is assumed that the lower limit for the array index is 1!
---

Example of Use of a Function

```
PROGRAM CLEAR  
  
REAL VA(2000)  
INTEGER INCA,NN;  
  
<Other program statements>  
  
INCA = 2  
NN = 1000  
  
CALL VCLRXXX(VA,INCA,NN)  
  
<Other program statements>  
  
END
```

This function causes each second element of the vector VA to be set to zero (increment is 2).

For vectors where the elements are stored in consecutive locations, the index increment is equal to 1. The flexibility to specify index increments is present to most of the functions.

For complex vectors, each complex equation is represented by two consecutive elements. This corresponds to the real and the imaginary part of the complex vector. The real element is immediately followed by the imaginary element, as the complex vector is represented in the rectangular coordinate system.

This means that for each index in the array there are one real and one imaginary element.

Example of Use of a Complex Function:

```
PROGRAM CVMULIPLY
```

```
COMPLEX VA(1:100)
```

```
COMPLEX VB(1:100)
```

```
COMPLEX VC(1:100)
```

```
<Other program statements>
```

```
CALL CVMULXX(VA,2,VB,2,VC,1,50,1)
```

```
<Other program statements>
```

```
END
```

This function causes each second complex vector in array VA to be multiplied with each second vector from VB. The results are stored in consecutive locations in VC. This function corresponds to mathematical multiplication of complex numbers.

## 2 USING THE ARRAY PROCESSING FUNCTIONS

The array processing functions can be called from FORTRAN. The array processing library is used to transfer the parameters from the call to the array processing instructions. Thus the array processing functions are linked to the main program at load time as a part of the program.

Writing a FORTRAN program for array processing with ND-500 array processing functions is much the same as using the FORTRAN equivalent for the array processing function. Before starting an array processing function, input and output arrays for the operations must be defined. Initialization of input arrays is also required. This means that data for processing must be placed in the input arrays for the actual array processing function. Then the array processing function may be called. The result of the operation is present in the output array when returning from an array processing function.

Calling the function APMOVE is a bit different from the other array processing functions, because a function, named LOCARG, must be called before APMOVE. See also page 80.

An example of calling array processing functions is given below. Detailed layout of the different array processing functions is given in chapter 5.

### Example of Creating a FORTRAN Program Using Array Processing Functions

#### Source Program in FORTRAN:

```

        PROGRAM DOKKT
C      Set name and size of arrays to be used.
        DIMENSION VA(100),VB(100),VC(100)
        INTEGER*2 I2(100)
        INTEGER*4 I4(100)
C      Initiate source array.
        I4(1) = 1
        I4(2) = 10
        I4(3) = 100
        I4(4) = 100
C      Get pointer to array I4.
        IADDA = LOCARG(I4)
C      Get pointer to array VC.
        IADDD = LOCARG(VC)
C      Set type of conversion with APMOVE and element count.
        IFTM = 0
        NN = 4
C      Convert 32 bit integer to single floating point and move.
        CALL APMOVE(IADDA,IADDD,IFTM,NN,*100)
100    CONTINUE
    
```

The program continues on next page...

...Continued from previous page

```

C      Set index increment and element count.
      INCC = 1
      NN   = 100
C      Clear the result array to be used in the next operation.
      CALL VCLRXXX(VA,INCC,NN,*101)
101   CONTINUE
      NN   = 4
C      Expand array VC with result in array VA.NC is returned.
      CALL VXPNDXX(VC,VA,NN,NC,*102)
102   CONTINUE

C      Set scalar value,index increments and element count.
      B    = 200.0
      INCA = 1
      INCC = 1
      NN   = NC
C      200.0 divided with each element of VA.Result in VB.
      CALL VDIVSXX(VA,INCA,B,VB,INCC,NN,*103)
103   CONTINUE
C      Set index increments and element count.
      INCA = 2
      INCB = 4
      INCC = 1
      NN   = 25
C      Add each second of VA to each fourth of VB.Result in VC.
      CALL VADDXXX(VA,INCA,VB,INCB,VC,INCC,NN,*104)
104   CONTINUE
      IADDD = LOCARG(I2)
      IADDA = LOCARG(VC)
      IFTM  = 4
C      Convert array VC to 16 bit integer.Result in I2.
      CALL APMOVE(IADDA,IADDD,IFTM,NN,*105)
105   CONTINUE
      IADDD = LOCARG(I4)
      IFTM  = 3
C      Convert array VC to 32 bit integer.Result in I4.
      CALL APMOVE(IADDA,IADDD,IFTM,NN,*106)
106   CONTINUE
C      Result of the operations in arrays VC,I4 and I2.
      WRITE (1,1000)
      DO FOR I=1,25
        WRITE (1,1001)VC(I),I4(I),I2(I)
      ENDDO
1000  FORMAT (' RESULT OF OPERATION IS :',/,
+ '..... REAL ..... INTEGER*4  INTEGER*2 .')
1001  FORMAT (3X,G12.7,5X,I11,5X,I6)
      END

```

Compiling the Program:

```
@FORTRAN-500 ↵  
ND-500 ANSI 77 FORTRAN COMPILER - 203054H  
FTN: COMPILE ↵  
SOURCE-FILE DOKKT ↵  
LIST-FILE ↵  
OBJECT-FILE "DOKKT" ↵  
- CPU TIME USED: 1.0 SECONDS. 67 LINES COMPILED.  
- NO MESSAGES  
- PROGRAM SIZE=401 DATA SIZE=2188 COMMON SIZE=0  
FTN: EXIT ↵
```

Loading the Program:

@LINKAGE-LOADER ↵

ND-Linkage-Loader - C            22. January    1982 Time: 15:5

N11: SET-DOMAIN DOKKT ↵

N11: LOAD DOKKT.ND-500-APF-LIB ↵

PROGRAM:.....555 P        DATA:.....4144 D

ND-500-APF-LIB

PROGRAM:.....1004 P       DATA:.....4500 D

NLL: CLOSE Y ↵

Segment no.....30        is linked

---

22. January    1982 Time: 15:5

Unsatisfied references :

None!

---

Defined symbols :

DOKKT.....4 P01 VADDXXX.....555 P01 VDIVSXX.....616 P01

VCLRXXX.....653 P01 VXPNDXX.....704 P01 APMOVE.....732 P01

LOCARG.....774 P01

Program:.....1004 P        Data:.....6500 D

N11: EXIT ↵



Executing the Program:

```
N500: DOKKT ↵  
  
RESULT OF OPERATION IS :  
..... REAL ..... INTEGER*4  INTEGER*2 .  
30.00000                30      30  
26.48485                26      26  
25.21531                25      25  
25.01976                25      25  
25.42088                25      25  
26.18768                26      26  
27.19480                27      27  
28.36829                28      28  
29.66173                29      29  
31.04448                31      31  
32.49554                32      32  
34.00000                34      34  
35.54700                35      35  
37.12843                37      37  
38.73813                38      38  
40.37133                40      40  
42.02425                42      42  
43.69392                43      43  
45.37788                45      45  
47.07420                47      47  
48.78122                48      48  
50.49760                50      50  
52.22221                52      52  
53.95409                53      53  
55.69241                55      55  
  
N500: EXIT ↵
```



3 ND-500 ARRAY PROCESSING FUNCTIONS PERFORMANCE

3.1 ND-560/1 PROCESSING PERFORMANCE

NAME	Typical execution time pr. loop (microsec.)			
	OPERATION	Improvement ratio to FTN function <sup>1)</sup>	Number of elements	
CFFTXXX	COMPLEX FAST FOURIER TRANSFORM	1024	3.80	62.25
CONVXXX	CONVOLUTION (CORRELATION)	150000	8.84	1.29
CVMULXX	COMPLEX VECTOR MULTIPLY	1500	3.20	8.55
DOTPRXX	DOT PRODUCT	1500	3.73	2.57
IBMFPCV	IBM TO ND FLOATING POINT CONVERT	1500	8.00	4.86
IMGBLD	IMAGE BUILD	1500	4.53	2.25
MAXMGVX	MAX. MAGNITUDE ELEMENT IN VECTOR	1500	5.43	1.54
MAXMINX	MAX. AND MIN. VALUE IN VECTOR	1500	5.50	2.38
MAXVXXX	MAX. VALUE IN VECTOR	1500	6.30	1.34
MINMGVX	MIN. MAGNITUDE ELEMENT IN VECTOR	1500	5.47	1.61
MINVXXX	MIN. VALUE IN VECTOR	1500	5.41	1.56
MXMNMGX	MAX. AND MIN. MAG. ELEMENT IN VECTOR	1500	4.54	2.62
NDFPCV	ND TO IBM FLOATING POINT CONVERT	1500	14.00	3.00
PREDICT	PREDICT	1500	4.82	2.85
RFFTXXX	REAL FAST FOURIER TRANSFORM	1024	2.40	58.60
SVEMGXX	SUM OF VECTOR ELEMENTS MAGNITUDE	1500	5.70	1.24
SVESQXX	SUM OF VECTOR ELEMENTS SQUARE	1500	4.20	1.93
SVEXXXX	SUM OF VECTOR ELEMENTS	1500	5.40	1.24
SVSXXX	SUM OF VECTOR ELEMENTS SIGNED SQUARE	1500	5.65	1.93
VABSXXX	VECTOR ABSOLUTE VALUE	1500	6.48	1.27
VADDXXX	VECTOR ADD	1500	6.00	1.93
VAVGABS	VECTOR AVERAGE ABSOLUTE VALUE	1500	4.00	1.65
VCLRXXX	VECTOR CLEAR	1500	6.34	0.80
VCOSXXX	VECTOR COSINE	1500	1.40	15.80
VDIVSXX	VECTOR SCALAR DIVIDE	1500	3.77	2.90
VDIVXXX	VECTOR DIVIDE	1500	4.09	3.19
VFLNZXX	VECTOR FIRST AND LAST NON-ZERO VALUE	1500	8.47	0.61
VGENXXX	VECTOR GENERATE	1500	7.44	1.29
VMAXMGX	VECTOR MAXIMUM MAGNITUDE	1500	6.00	2.28
VMAXXXX	VECTOR MAXIMUM	1500	6.32	2.07
VMINMGX	VECTOR MINIMUM MAGNITUDE	1500	6.00	2.28
VMINXXX	VECTOR MINIMUM	1500	6.32	2.07
VMOVXXX	VECTOR MOVE	1500	6.39	1.16
VMULXXX	VECTOR MULTIPLY	1500	5.93	1.92
VNEGXXX	VECTOR NEGATIVE	1500	7.40	1.16
VNMOSXX	VECTOR SINC INTERPOLATION	1500	3.88	21.68

<sup>1)</sup> (Time used by machine code) / (Time used by microcode).

<sup>2)</sup> ASM - ND-500 assembler.

ND-500 SINGLE PRECISION ARRAY PROCESSING FUNCTIONS  
ND-500 ARRAY PROCESSING FUNCTIONS PERFORMANCE

NAME	OPERATION	Typical execution time pr. loop (microsec.)		
		Improvement ratio to FTN function <sup>1)</sup>	Number of elements	
VNMOXXX	VECTOR LINEAR INTERPOLATION	1500	3.12	8.16
VSADDXX	VECTOR SCALAR ADD	1500	5.67	1.64
VSINXXX	VECTOR SINE	1500	1.40	15.09
VSMADDX	VECTOR SCALAR MULTIPLY AND ADD	1500	5.30	2.21
VSMULXX	VECTOR SCALAR MULTIPLY	1500	5.68	1.64
VSQRTXX	VECTOR SQUARE ROOT	1500	1.78	8.85
VSQXXX	VECTOR SQUARE	1500	5.10	1.93
VSSQXXX	VECTOR SIGNED SQUARE	1500	6.20	1.93
VSUBXXX	VECTOR SUBTRACT	1500	6.00	1.92
VSWAPXX	VECTOR SWAP	1500	5.20	2.00
VTAPERX	VECTOR TAPER	1500	3.00	2.07
VXPNDXX	VECTOR EXPAND	1500	4.07	1.77
WIENERX	WIENER FILTER	81	3.03	365.40
XBTMUX	DISPLAY PROCESSOR FUNCTION	1500	5.45	50.00

NAME	OPERATION	Typical execution time pr. loop (microsec.)		
		Improvement ratio to ASM function <sup>2)</sup>	Number of elements	
APMOVE	CONVERT AND MOVE FORMAT 0	1500	2.68	1.38
APMOVE	CONVERT AND MOVE FORMAT 1	1500	2.38	1.53
APMOVE	CONVERT AND MOVE FORMAT 2 & 5	1500	1.17	0.89
APMOVE	CONVERT AND MOVE FORMAT 3	1500	2.57	1.38
APMOVE	CONVERT AND MOVE FORMAT 4	1500	2.86	1.53
DMX B	DEMULPLEX SEGMENT B	1500	2.66	3.01

The figures have been taken from a ND-560/1 with 128 k byte cache memory.

<sup>1)</sup> (Time used by machine code) / (Time used by microcode).

<sup>2)</sup> ASM - ND-500 assembler.

3.2 ND-570/2 PROCESSING PERFORMANCE

NAME	Typical execution time pr. loop (microsec.)			
	OPERATION	Improvement ratio to FTN function <sup>1)</sup>	Number of elements	
CFFTXXX	COMPLEX FAST FOURIER TRANSFORM		1024	3.35
CONVXXX	CONVOLUTION (CORRELATION)		150000	6.50
CVMULXX	COMPLEX VECTOR MULTIPLY		1500	2.60
DOTPRXX	DOT PRODUCT		1500	3.40
IBMFPCV	IBM TO ND FLOATING POINT CONVERT		1500	7.15
IMGBLD	IMAGE BUILD		1500	3.50
MAXMGVX	MAX. MAGNITUDE ELEMENT IN VECTOR		1500	5.56
MAXMINX	MAX. AND MIN. VALUE IN VECTOR		1500	3.98
MAXVXXX	MAX. VALUE IN VECTOR		1500	4.64
MINMGVX	MIN. MAGNITUDE ELEMENT IN VECTOR		1500	5.62
MINVXXX	MIN. VALUE IN VECTOR		1500	4.15
MXMNMGX	MAX. AND MIN. MAG. ELEMENT IN VECTOR		1500	4.31
NDFPCV	ND TO IBM FLOATING POINT CONVERT		1500	9.95
PREDICT	PREDICT		1500	4.78
RFFTXXX	REAL FAST FOURIER TRANSFORM		1024	2.08
SVEMGXX	SUM OF VECTOR ELEMENTS MAGNITUDE		1500	5.25
SVESQXX	SUM OF VECTOR ELEMENTS SQUARE		1500	3.70
SVEXXX	SUM OF VECTOR ELEMENTS		1500	4.85
SVSXXXX	SUM OF VECTOR ELEMENTS SIGNED SQUARE		1500	5.25
VABSXXX	VECTOR ABSOLUTE VALUE		1500	5.35
VADDXXX	VECTOR ADD		1500	3.70
VAVGABS	VECTOR AVERAGE ABSOLUTE VALUE		1500	4.40
VCLRXXX	VECTOR CLEAR		1500	5.60
VCOSXXX	VECTOR COSINE		1500	1.47
VDIVSXX	VECTOR SCALAR DIVIDE		1500	2.45
VDIVXXX	VECTOR DIVIDE		1500	2.82
VFLNZXX	VECTOR FIRST AND LAST NON-ZERO VALUE		1500	7.62
VGENXXX	VECTOR GENERATE		1500	5.25
VMAXMGX	VECTOR MAXIMUM MAGNITUDE		1500	3.68
VMAXXXX	VECTOR MAXIMUM		1500	3.75
VMINMGX	VECTOR MINIMUM MAGNITUDE		1500	3.68
VMINXXX	VECTOR MINIMUM		1500	3.75
VMOVXXX	VECTOR MOVE		1500	5.50
VMULXXX	VECTOR MULTIPLY		1500	3.70
VNEGXXX	VECTOR NEGATIVE		1500	5.65
VNMOSXX	VECTOR SINC INTERPOLATION		150	3.00

<sup>1)</sup> (Time used by machine code) / (Time used by microcode).

<sup>2)</sup> ASM - ND-500 assembler.

ND-500 SINGLE PRECISION ARRAY PROCESSING FUNCTIONS  
ND-500 ARRAY PROCESSING FUNCTIONS PERFORMANCE

NAME	Typical execution time pr. loop (microsec.)			
	OPERATION	Improvement ratio to FTN function <sup>1)</sup>		
	Number of elements			
VNMOXXX	VECTOR LINEAR INTERPOLATION	1500	2.38	5.52
VSADDDX	VECTOR SCALAR ADD	1500	3.25	1.53
VSINXXX	VECTOR SINE	1500	1.47	10.60
VSMADDDX	VECTOR SCALAR MULTIPLY AND ADD	1500	3.40	1.90
VSMULXX	VECTOR SCALAR MULTIPLY	1500	3.27	1.50
VSQRTXX	VECTOR SQUARE ROOT	1500	1.55	6.02
VSQXXXX	VECTOR SQUARE	1500	4.20	1.18
VSSQXXX	VECTOR SIGNED SQUARE	1500	5.70	1.18
VSUBXXX	VECTOR SUBTRACT	1500	3.70	1.60
VSWAPXX	VECTOR SWAP	1500	2.80	2.10
VTAPERX	VECTOR TAPER	1500	2.53	1.37
VXPNDXX	VECTOR EXPAND	1500	3.30	1.13
WIENERX	WIENER FILTER	81	1.90	251.85
XBTMUX	DISPLAY PROCESSOR FUNCTION	1500	4.45	32.10

NAME	Typical execution time pr. loop (microsec.)			
	OPERATION	Improvement ratio to ASM function <sup>2)</sup>		
	Number of elements			
APMOVE	CONVERT AND MOVE FORMAT 0	1500	1.83	1.24
APMOVE	CONVERT AND MOVE FORMAT 1	1500	2.40	1.00
APMOVE	CONVERT AND MOVE FORMAT 2 & 5	1500	1.73	0.49
APMOVE	CONVERT AND MOVE FORMAT 3	1500	1.90	1.25
APMOVE	CONVERT AND MOVE FORMAT 4	1500	3.68	0.75
DMXB	DEMULTIPLY SEGMENT B	1500	2.60	1.94
VTAPERX	VECTOR TAPER	1500	2.53	1.37

The figures have been taken from a ND-570/2 with 32k bytes of cache memory.

<sup>1)</sup> (Time used by machine code) / (Time used by microcode).

<sup>2)</sup> ASM - ND-500 assembler.

## 4 ARRAY PROCESSING FUNCTIONS

### 4.1 INTRODUCTION

This chapter contains a listing of each array processing function. For each routine, the required parameter list for calling the array processing function is included together with definitions.

The ND-500 array processing functions are implemented as one machine instruction, except the functions DMXB, WIENERX, CFFTXXX and RFFTXXX, which are partly microcoded. These are implemented as different instructions to be executed consecutively.

The function DMXB uses two instruction codes. Functions XBTMUX and IMGBLD use a third instruction code. All of the other functions use a fourth instruction code. The contents of the record register are the only difference between the functions and are used to distinguish between them.

For each routine, an identification number is given as a cross reference between the object code and the array processing function. This identification number is given as two octal numbers :  
'Ident (R:I) : xxx:nnnnnB'. 'xxx' are the contents of the record register. 'nnnnn' is the instruction code used for the processing function.

The library for the ND-500 array processing functions consists of one routine for each of the array processing functions. Each routine builds a data stack used by the array processing function to find addresses of input and output arrays, scalar values or addresses, index increments and element counts.

An address is a pointer to the logical memory for both input and output arrays.

Scalars to be used in an operation are located in the data stack as 32 bit floating point numbers.

Scalars to be returned from an operation are returned to the address given in the data stack.

Index increments and element counts are given in the data stack as 32 bit integers.

It is not necessary to use the alternative return argument when calling a routine.

## 4.2 VECTOR ADD (VADDXXX)

### Format

VADDXXX(VA,INCA,VB,INCB,VC,INCC,NN,\*)            Ident (R:I) : 001:177517B

### Explanation

Add the corresponding elements of two vectors.  $VC_n = VA_n + VB_n$ , 'n' is the element index.

### Parameters

VA        : Name of input vector VA.  
INCA     : VA index increment.  
VB        : Name of input vector VB.  
INCB     : VB index increment.  
VC        : Name of output vector VC.  
INCC     : VC index increment.  
NN        : Element count.

### Listing

```

SUBROUTINE VADDXXX(VA,INCA,VB,INCB,VC,INCC,NN,*)
DIMENSION VA(1),VB(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1,NN
    VC(IC) = VB(IB) + VA(IA)
    IA = IA + INCA
    IB = IB + INCB
    IC = IC + INCC
ENDDO
RETURN 1
END

```



### 4.3 VECTOR SUBTRACT (VSUBXXX)

#### Format

VSUBXXX(VA, INCA, VB, INCB, VC, INCC, NN, \*)            Ident (R:I) : 002:177517B

#### Explanation

Subtract the corresponding elements of two vectors.  $VC_n = VB_n - VA_n$ , 'n' is the element index.

#### Parameters

VA        : Name of input vector VA.  
INCA      : VA index increment.  
VB        : Name of input vector VB.  
INCB      : VB index increment.  
VC        : Name of output vector VC.  
INCC      : VC index increment.  
NN        : Element count.

#### Listing

```
SUBROUTINE VSUBXXX(VA, INCA, VB, INCB, VC, INCC, NN, *)  
  DIMENSION VA(1), VB(1), VC(1)  
  IA = 1  
  IB = 1  
  IC = 1  
  DO FOR M = 1, NN  
    VC(IC) = VB(IB) - VA(IA)  
    IA = IA + INCA  
    IB = IB + INCB  
    IC = IC + INCC  
  ENDDO  
  RETURN 1  
  END
```

#### 4.4 VECTOR MULTIPLY (VMULXXX)

##### Format

VMULXXX(VA, INCA, VB, INCB, VC, INCC, NN, \*)            Ident (R:I) : 003:177517B

##### Explanation

Multiply the corresponding elements of two vectors.  $VC_n = VB_n * VA_n$ , 'n' is the element index.

##### Parameters

VA        : Name of input vector VA.  
INCA     : VA index increment.  
VB        : Name of input vector VB.  
INCB     : VB index increment.  
VC        : Name of output vector VC.  
INCC     : VC index increment.  
NN        : Element count.

##### Listing

```

SUBROUTINE VMULXXX(VA, INCA, VB, INCB, VC, INCC, NN, *)
DIMENSION VA(1), VB(1), VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1, NN
  VC(IC) = VB(IB) * VA(IA)
  IA = IA + INCA
  IB = IB + INCB
  IC = IC + INCC
ENDDO
RETURN 1
END

```

#### 4.5 VECTOR DIVIDE (VDIVXXX)

##### Format

VDIVXXX(VA,INCA,VB,INCB,VC,INCC,NN,\*)      Ident (R:I) : 004:177517B

##### Explanation

Divide the corresponding elements of two vectors.  $VC_n = VB_n/VA_n$ , 'n' is the element index.

##### Parameters

VA     : Name of input vector VA.  
INCA   : VA index increment.  
VB     : Name of input vector VB.  
INCB   : VB index increment.  
VC     : Name of output vector VC.  
INCC   : VC index increment.  
NN     : Element count.

##### Listing

```
SUBROUTINE VDIVXXX(VA,INCA,VB,INCB,VC,INCC,NN,*)
DIMENSION VA(1),VB(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = VB(IB) / VA(IA)
  IA = IA + INCA
  IB = IB + INCB
  IC = IC + INCC
ENDDO
RETURN 1
END
```

#### 4.6 VECTOR MAXIMUM (VMAXXXX)

##### Format

VMAXXXX(VA,INCA,VB,INCB,VC,INCC,NN,\*)                    Ident (R:I) : 005:177517B

##### Explanation

Form a vector from the maximum value of each corresponding pair of elements of two vectors.  $VC_n = VA_n$  if  $VA_n > VB_n$ , else  $VC_n = VB_n$ . 'n' is the element index.

##### Parameters

VA        : Name of input vector VA.  
INCA     : VA index increment.  
VB        : Name of input vector VB.  
INCB     : VB index increment.  
VC        : Name of output vector VC.  
INCC     : VC index increment.  
NN        : Element count.

##### Listing

```

SUBROUTINE VMAXXXX(VA,INCA,VB,INCB,VC,INCC,NN,*)
DIMENSION VA(1),VB(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = AMAX1(VA(IA),VB(IB))
  IA = IA + INCA
  IB = IB + INCB
  IC = IC + INCC
ENDDO
RETURN 1
END

```

#### 4.7 VECTOR MINIMUM (VMINXXX)

##### Format

VMINXXX(VA,INCA,VB,INCB,VC,INCC,NN,\*)            Ident (R:I) : 006:177517B

##### Explanation

Form a vector from the minimum value of each corresponding pair of elements of two vectors.  $VC_n = VA_n$  if  $VA_n < VB_n$ , else  $VC_n = VB_n$ . 'n' is the element index.

##### Parameters

VA        : Name of input vector VA.  
INCA      : VA index increment.  
VB        : Name of input vector VB.  
INCB      : VB index increment.  
VC        : Name of output vector VC.  
INCC      : VC index increment.  
NN        : Element count.

##### Listing

```
SUBROUTINE VMINXXX(VA,INCA,VB,INCB,VC,INCC,NN,*)  
  DIMENSION VA(1),VB(1),VC(1)  
  IA = 1  
  IB = 1  
  IC = 1  
  DO FOR M = 1,NN  
    VC(IC) = AMIN1(VA(IA),VB(IB))  
    IA = IA + INCA  
    IB = IB + INCB  
    IC = IC + INCC  
  ENDDO  
  RETURN 1  
END
```

**4.8 VECTOR MAXIMUM MAGNITUDE (VMAXGX)**Format

VMAXGX(VA,INCA,VB,INCB,VC,INCC,NN,\*)      Ident (R:I) : 007:177517B

Explanation

Form a vector from the maximum absolute value of each corresponding pair of elements of two vectors.  $VC_n = |VA_n|$  if  $|VA_n| > |VB_n|$ , else  $VC_n = |VB_n|$ . 'n' is the element index.

Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VB : Name of input vector VB.  
 INCB : VB index increment.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

Listing

```

SUBROUTINE VMAXGX(VA,INCA,VB,INCB,VC,INCC,NN,*)
DIMENSION VA(1),VB(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = AMAX1(ABS(VA(IA)),ABS(VB(IB)))
  IA = IA + INCA
  IB = IB + INCB
  IC = IC + INCC
ENDDO
RETURN 1
END

```

#### 4.9 VECTOR MINIMUM MAGNITUDE (VMINMGX)

##### Format

VMINMGX(VA,INCA,VB,INCB,VC,INCC,NN,\*)            Ident (R:I) : 010:177517B

##### Explanation

Form a vector from the minimum absolute value of each corresponding pair of elements of two vectors.  $VC_n = |VA_n|$  if  $|VA_n| < |VB_n|$ , else  $VC_n = |VB_n|$ . 'n' is the element index.

##### Parameters

VA        : Name of input vector VA.  
INCA      : VA index increment.  
VB        : Name of input vector VB.  
INCB      : VB index increment.  
VC        : Name of output vector VC.  
INCC      : VC index increment.  
NN        : Element count.

##### Listing

```
SUBROUTINE VMINMGX(VA,INCA,VB,INCB,VC,INCC,NN,*)
DIMENSION VA(1),VB(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = AMIN1(ABS(VA(IA)),ABS(VB(IB)))
  IA = IA + INCA
  IB = IB + INCB
  IC = IC + INCC
ENDDO
RETURN 1
END
```

#### 4.10 VECTOR SQUARE (VSQXXXX)

##### Format

VSQXXXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 042:177517B

##### Explanation

Square the elements of a vector.  $VC_n = (VA_n)^2$ . 'n' is the element index.

##### Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

##### Listing

```

SUBROUTINE VSQXXXX(VA,INCA,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = VA(IA)**2
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END

```



#### 4.11 VECTOR SIGNED SQUARE (VSSQXXX)

##### Format

VSSQXXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 011:177517B

##### Explanation

Multiply each element of a vector with the absolute value of itself.  
 $VC_n = VAn * |VAn|$ . 'n' is the element index.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE VSSQXXX(VA,INCA,VC,INCC,NN,*)
  DIMENSION VA(1),VC(1)
  IA = 1
  IC = 1
  DO FOR M = 1,NN
    VC(IC) = SIGN(VA(IA)**2,VA(IA))
    IA = IA + INCA
    IC = IC + INCC
  ENDDO
  RETURN 1
END
```

**4.12 VECTOR ABSOLUTE VALUE (VABSXXX)**Format

VABSXXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 012:177517B

Explanation

Form a vector from the absolute values of the elements in a vector.  
 $VC_n = |VA_n|$ . 'n' is the element index.

Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

Listing

```

SUBROUTINE VABSXXX(VA,INCA,VC,INCC,NN,*)
  DIMENSION VA(1),VC(1)
  IA = 1
  IC = 1
  DO FOR M = 1,NN
    VC(IC) = ABS(VA(IA))
    IA = IA + INCA
    IC = IC + INCC
  ENDDO
  RETURN 1
END

```

#### 4.13 VECTOR SQUARE ROOT (VSQRTXX)

##### Format

VSQRTXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 013:177517B

##### Explanation

Take the square roots of the elements in a vector.  $VC_n = \sqrt{VA_n}$ . 'n' is the element index.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE VSQRTXX(VA,INCA,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
    VC(IC) = SQRT(VA(IA))
    IA = IA + INCA
    IC = IC + INCC
ENDDO
RETURN 1
END
```

#### 4.14 VECTOR SINE (VSINXXX)

##### Format

VSINXXX(VA, INCA, VC, INCC, NN, \*)

Ident (R:I) : 014:177517B

##### Explanation

Compute the sine of the elements of a vector.  $VC_n = \sin(VA_n)$ . 'n' is the element index. The arguments in VA must be in radians.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE VSINXXX(VA, INCA, VC, INCC, NN, *)
DIMENSION VA(1), VC(1)
IA = 1
IC = 1
DO FOR M = 1, NN
    VC(IC) = SIN(VA(IA))
    IA = IA + INCA
    IC = IC + INCC
ENDDO
RETURN 1
END
```

#### 4.15 VECTOR COSINE (VCOSXXX)

##### Format

VCOSXXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 015:177517B

##### Explanation

Compute the cosine of the elements of a vector.  $VC_n = \cos(VA_n)$ . 'n' is the element index. The arguments in VA must be in radians.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE VCOSXXX(VA,INCA,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = COS(VA(IA))
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END
```

**4.16 VECTOR MOVE (VMOVXXX)****Format**

VMOVXXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 016:177517B

**Explanation**

Move the elements from one vector into another. VCn = VAn, 'n' is the element index.

**Parameters**

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

**Listing**

```

SUBROUTINE VMOVXXX(VA,INCA,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = VA(IA)
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END

```

#### 4.17 VECTOR SWAP (VSWAPXX)

##### Format

VSWAPXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 063:177517B

##### Explanation

Swap the elements between two vectors.  $VA_n \leftrightarrow VB_n$  and  $VB_n \leftrightarrow VA_n$ , 'n' is the element index.

##### Parameters

VA : Name of input and output vector VA.  
INCA : VA index increment.  
VC : Name of input and output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE VSWAPXX(VA,INCA,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
REAL HOLD
IA = 1
IC = 1
DO FOR M = 1,NN
  HOLD = VC(IC)
  VC(IC) = VA(IA)
  VA(IA) = HOLD
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END
```

**4.18 VECTOR NEGATIVE (VNEGXXX)****Format**

VNEGXXX(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 064:177517B

**Explanation**

Form a vector from the elements of another vector multiplied with -1.  
VCn = -VAn, 'n' is the element index.

**Parameters**

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

**Listing**

```

SUBROUTINE VNEGXXX(VA,INCA,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = - VA(IA)
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END

```



#### 4.19 ND TO IBM FLOATING POINT CONVERT (NDFPCV)

##### Format

NDFPCV(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 017:177517B

##### Explanation

Convert the elements of a vector into ND floating point format to IBM floating point format. Symbolically this can be represented by the formula:  $VC_n = IBMFP(VA_n)$ , 'n' denotes the element index.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE NDFPCV(VA,INCA,VC,INCC,NN,*)
REAL VA(1),VC(1),TEMP
INTEGER MANT,CHAR,HIDBIT,HEXCHR,RSHT,ITEMP
INTEGER ROUND(3)
EQUIVALENCE (TEMP,ITEMP)
DATA MASK1 /00017777777B/
DATA HIDBIT /00020000000B/
DATA MASK2 /17777777777B/
DATA MASK3 /20000000000B/
DATA ROUND /1,2,4/
IA = 1
IC = 1
DO FOR M = 1,NN
  TEMP = VA(IA)
  IF (ITEMP .EQ. 0) THEN
    VC(IC) = 0.0
    GO TO 100
  ENDIF
  MANT = (IAND(ITEMP,MASK1) + HIDBIT)*2
  CHAR = IAND(ITEMP,MASK2)
  CHAR = ISHFT(CHAR,-22)
  HEXCHR = CHAR/4
  RSHT = 4 - MOD(CHAR,4)
  IF (RSHT .NE. 4) THEN
    MANT = MANT + ROUND(RSHT)
    MANT = ISHFT(MANT,-RSHT)
    HEXCHR = HEXCHR + 1
  ENDIF
  IF (HEXCHR .GT. 127) THEN
```

```
        HEXCHR = 127
        MANT = 00077777777B
    ENDIF
    ITEMP = ISHFT(HEXCHR,24) + MANT
    IF (VA(IA) .LT. 0.) ITEMP = IOR(ITEMP,MASK3)
    VC(IC) = TEMP
100 CONTINUE
    IA = IA + INCA
    IC = IC + INCC
    ENDDO
    RETURN 1
    END
```

**4.20 IBM TO ND FLOATING POINT CONVERT (IBMFPCV)**

Format

IBMFPCV(VA,INCA,VC,INCC,NN,\*)

Ident (R:I) : 020:177517B

Explanation

To convert the elements of a vector in IBM floating point format into ND floating point format. Symbolically this can be represented by the formula: VCn = NDFP(VAn), 'n' denotes the element index.

Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

Listing

```

SUBROUTINE IBMFPCV(VA,INCA,VC,INCC,NN,*)
REAL VA(1),VC(1),TEMP
INTEGER MANTSFT,CHAR,RSHFT,ITEMP,SHFTCNT
EQUIVALENCE (TEMP,ITEMP)
DATA MASK1 /17700000000B/
DATA MASK2 /00077777777B/
DATA MASK3 /20000000000B/
DATA MASK4 /00074000000B/
IA = 1
IC = 1
DO FOR M = 1,NN
  SHFTCNT = -1
  TEMP = VA(IA)
  IF (ITEMP .EQ. 0) THEN
    VC(IC) = 0.0
    GO TO 100
  ENDIF
  CHAR = IAND(ITEMP,MASK1)
  CHAR = ISHFT(CHAR,-24)*4
  MANTSFT = IAND(ITEMP,MASK4)
  MANTSFT = ISHFT(MANTSFT,-20)
  IF (MANTSFT.GT.0) SHFTCNT=4
  IF (MANTSFT.GT.1) SHFTCNT=3
  IF (MANTSFT.GT.3) SHFTCNT=2
  IF (MANTSFT.GT.7) SHFTCNT=1
  CHAR = CHAR-SHFTCNT+1
  ITEMPT = ISHFT(ITEMP,SHFTCNT)
  ITEMPT = IAND (ITEMPT,MASK2)
  ITEMPT = ISHFT(ITEMPT,-2) + ISHFT(CHAR,22)

```

```
IF ( VA(IA) .LT. 0. ) ITEMP = IOR (ITEMP, MASK3)
VC(IC) = TEMP
IF(SHFTCNT.EQ.-1)VC(IC)=1777777777B
100 CONTINUE
IA = IA + INCA
IC = IC + INCC
ENDDO
RETURN 1
END
```

#### 4.21 SUM OF VECTOR ELEMENTS (SVEXXXX)

##### Format

SVEXXXX(VA,INCA,VC,NN,\*)

Ident (R:I) : 021:177517B

##### Explanation

Add the elements of a vector.  $VC = VA_1 + VA_2 + \dots + VAnn$ , 'nn' is the element count.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output scalar VC.  
NN : Element count.

##### Listing

```
SUBROUTINE SVEXXXX(VA,INCA,VC,NN,*)
  DIMENSION VA(1)
  IA = 1
  SUM = 0.0
  DO FOR M = 1,NN
    SUM = SUM + VA(IA)
    IA = IA + INCA
  ENDDO
  VC = SUM
  RETURN 1
  END
```

**4.22 SUM OF VECTOR ELEMENTS MAGNITUDE (SVEMGXX)**Format

SVEMGXX(VA,INCA,VC,NN,\*)

Ident (R:I) : 065:177517B

Explanation

Form the sum of the absolute values of the elements of a vector.

$$VC = |VA_1| + |VA_2| + \dots + |VAnn|$$
, 'nn' is the element count.Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output scalar VC.  
 NN : Element count.

Listing

```

SUBROUTINE SVEMGXX(VA,INCA,VC,NN,*)
DIMENSION VA(1)
IA = 1
SUM = 0.0
DO FOR M = 1,NN
  SUM = SUM + ABS(VA(IA))
  IA = IA + INCA
ENDDO
VC = SUM
RETURN 1
END

```

#### 4.23 SUM OF VECTOR ELEMENTS SQUARE (SVESQXX)

##### Format

SVESQXX(VA,INCA,VC,NN,\*)

Ident (R:I) : 066:177517B

##### Explanation

Form the sum of the squared elements of a vector.

$VC = (VA_1)^2 + (VA_2)^2 + \dots + (VAnn)^2$ , 'nn' is the element count.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output scalar VC.  
NN : Element count.

##### Listing

```
SUBROUTINE SVESQXX(VA,INCA,VC,NN,*)  
DIMENSION VA(1)  
IA = 1  
SUM= 0.0  
DO FOR M = 1,NN  
    SUM=SUM + VA(IA)**2  
    IA = IA + INCA  
ENDDO  
VC=SUM  
RETURN 1  
END
```

**4.24 SUM OF VECTOR ELEMENTS SIGNED SQUARE (SVSXXXX)**Format

SVSXXXX(VA,INCA,VC,NN,\*)

Ident (R:I) : 022:177517B

Explanation

Form the sum of the elements of a vector, where each element at first is multiplied with the absolute value of itself.

$$VC = VA_1 * |VA_1| + VA_2 * |VA_2| + \dots + VAnn * |VAnn|$$

'nn' is the element count.

Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output scalar VC.  
 NN : Element count.

Listing

```

SUBROUTINE SVSXXXX(VA,INCA,VC,NN,*)
DIMENSION VA(1)
IA = 1
SUM= 0.0
DO FOR M = 1,NN
  SUM=SUM + SIGN(VA(IA)*VA(IA),VA(IA))
  IA = IA + INCA
ENDDO
VC=SUM
RETURN 1
END

```



#### 4.25 VECTOR AVERAGE ABSOLUTE VALUE (VAVGABS)

##### Format

VAVGABS(VA,INCA,VC,NN,\*)

Ident (R:I) : 023:177517B

##### Explanation

Form the mean value of the absolute values of the elements of a vector.  $VC = (|VA_1| + |VA_2| + \dots + |VAnn|) / nn$ , 'nn' is the element count.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output scalar VC.  
NN : Element count.

##### Listing

```
SUBROUTINE VAVGABS(VA,INCA,VC,NN,*)
  DIMENSION VA(1)
  IA = 1
  SUMABS = 0.0
  DO FOR I = 1,NN
    SUMABS = SUMABS + ABS(VA(IA))
    IA = IA + INCA
  ENDDO
  VC = SUMABS/NN
  RETURN 1
END
```

**4.26 MAXIMUM VALUE IN VECTOR (MAXVXXX)**Format

MAXVXXX(VA,INCA,VC,NN,\*)

Ident (R:I) : 024:177517B

Explanation

Scan a vector for its element with maximum value and return this ( $VC_1$ ) together with the corresponding index ( $VC_2$ ).

Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
NN : Element count.

Listing

```

SUBROUTINE MAXVXXX(VA,INCA,VC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
VC(1) = VA(IA)
VC(2) = IA
DO FOR M = 2,NN
  IA = IA + INCA
  IF (VA(IA) .GT. VC(1)) THEN
    VC(1) = VA(IA)
    VC(2) = IA
  ENDIF
ENDDO
RETURN 1
END

```

#### 4.27 MINIMUM VALUE IN VECTOR (MINVXXX)

##### Format

MINVXXX(VA,INCA,VC,NN,\*)

Ident (R:I) : 025:177517B

##### Explanation

Scan a vector for its element with minimum value and return this (VC<sub>1</sub>) together with the corresponding index (VC<sub>2</sub>).

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
NN : Element count.

##### Listing

```
SUBROUTINE MINVXXX(VA,INCA,VC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
VC(1) = VA(IA)
VC(2) = IA
DO FOR M = 2,NN
  IA = IA + INCA
  IF (VA(IA) .LT. VC(1)) THEN
    VC(1) = VA(IA)
    VC(2) = IA
  ENDIF
ENDDO
RETURN 1
END
```

**4.28 MAXIMUM MAGNITUDE ELEMENT IN VECTOR (MAXMGVX)**Format

MAXMGVX(VA,INCA,VC,NN,\*) Ident (R:I) : 026:177517B

Explanation

Scan a vector for its element with maximum absolute value, and return this (VC<sub>1</sub>) together with the corresponding index (VC<sub>2</sub>).

Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output vector VC.  
 NN : Element count.

Listing

```

SUBROUTINE MAXMGVX(VA,INCA,VC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
VC(1) = ABS(VA(IA))
VC(2) = IA
DO FOR M = 2,NN
  IA = IA + INCA
  VAABS = ABS(VA(IA))
  IF (VAABS .GT. VC(1)) THEN
    VC(1) = VAABS
    VC(2) = IA
  ENDIF
ENDDO
RETURN 1
END

```

#### 4.29 MINIMUM MAGNITUDE ELEMENT IN VECTOR (MINMGVX)

##### Format

MINMGVX(VA,INCA,VC,NN,\*)

Ident (R:I) : 027:177517B

##### Explanation

Scan a vector for its element with minimum absolute value, and return this (VC<sub>1</sub>) together with the corresponding index (VC<sub>2</sub>).

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
NN : Element count.

##### Listing

```
SUBROUTINE MINMGVX(VA,INCA,VC,NN,*)
  DIMENSION VA(1),VC(1)
  IA = 1
  VC(1) = ABS(VA(IA))
  VC(2) = IA
  DO FOR M = 2,NN
    IA = IA + INCA
    VAABS = ABS(VA(IA))
    IF (VAABS .LT. VC(1)) THEN
      VC(1) = VAABS
      VC(2) = IA
    ENDIF
  ENDDO
  RETURN 1
END
```

#### 4.30 MAXIMUM AND MINIMUM VALUE IN VECTOR (MAXMINX)

##### Format

MAXMINX(VA,INCA,VC,NN,\*)

Ident (R:I) : 030:177517B

##### Explanation

Scan a vector for its element with maximum value and its element with minimum value. The maximum value is returned in VC<sub>1</sub>, and with index for VA in VC<sub>3</sub>. The minimum value is returned in VC<sub>2</sub>, and with index for VA in VC<sub>4</sub>.

##### Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 VC : Name of output vector VC.  
 NN : Element count.

##### Listing

```

SUBROUTINE MAXMINX(VA,INCA,VC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
VC(1) = VA(IA)
VC(2) = VA(IA)
VC(3) = IA
VC(4) = IA
DO FOR M = 2,NN
  IA = IA + INCA
  IF (VA(IA) .GT. VC(1)) THEN
    VC(1) = VA(IA)
    VC(3) = IA
  ELSEIF (VA(IA) .LT. VC(3)) THEN
    VC(2) = VA(IA)
    VC(4) = IA
  ENDIF
ENDDO
RETURN 1
END

```

#### 4.31 MAXIMUM AND MINIMUM MAGNITUDE ELEMENT IN VECTOR (MXMNMGX)

##### Format

MXMNMGX(VA,INCA,VC,NN,\*)

Ident (R:I) : 031:177517B

##### Explanation

Scan a vector for its element with absolute maximum value and its element with minimum absolute value. The maximum value is returned in VC<sub>1</sub>, and with index for VA in VC<sub>3</sub>. The minimum value is returned in VC<sub>2</sub>, and with index for VA in VC<sub>4</sub>.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VC : Name of output vector VC.  
NN : Element count.

##### Listing

```
SUBROUTINE MXMNMGX(VA,INCA,VC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
VC(1) = ABS(VA(IA))
VC(2) = ABS(VA(IA))
VC(3) = IA
VC(4) = IA
DO FOR M = 2,NN
  IA = IA + INCA
  VAABS = ABS(VA(IA))
  IF (VAABS .GT. VC(1)) THEN
    VC(1) = VAABS
    VC(3) = IA
  ELSEIF (VAABS .LT. VC(3)) THEN
    VC(2) = VAABS
    VC(4) = IA
  ENDIF
ENDDO
RETURN 1
END
```

#### 4.32 VECTOR SCALAR ADD (VSADXX)

##### Format

VSADXX(VA, INCA, B, VC, INCC, NN, \*)

Ident (R:I) : 032:177517B

##### Explanation

Add the elements of a vector together with a scalar value.

$VC_n = VA_n + b$ , where 'b' denotes the scalar, and 'n' denotes the element index.

##### Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 B : Scalar B.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

##### Listing

```

SUBROUTINE VSADXX(VA, INCA, B, VC, INCC, NN, *)
DIMENSION VA(1), VC(1)
IA = 1
IC = 1
DO FOR M = 1, NN
  VC(IC) = B + VA(IA)
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END

```



### 4.33 VECTOR SCALAR MULTIPLY (VSMULXX)

#### Format

VSMULXX(VA,INCA,B,VC,INCC,NN,\*)

Ident (R:I) : 033:177517B

#### Explanation

Multiply the elements of a vector with a scalar value.

$VC_n = VA_n * b$ , where 'b' denotes the scalar, and 'n' denotes the element index.

#### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
B : Scalar B.  
VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

#### Listing

```
SUBROUTINE VSMULXX(VA,INCA,B,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = B * VA(IA)
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END
```

**4.34 VECTOR SCALAR DIVIDE (VDIVSXX)**Format

VDIVSXX(VA,INCA,B,VC,INCC,NN,\*)

Ident (R:I) : 034:177517B

Explanation

Form a vector from a scalar value divided with the elements of another vector.  $VC_n = b/VA_n$ , 'b' denotes the scalar and 'n' denotes the element index.

Parameters

VA : Name of input vector VA.  
 INCA : VA index increment.  
 B : Scalar B.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

Listing

```

SUBROUTINE VDIVSXX(VA,INCA,B,VC,INCC,NN,*)
DIMENSION VA(1),VC(1)
IA = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = B / VA(IA)
  IA = IA + INCA
  IC = IC + INCC
ENDDO
RETURN 1
END

```

#### 4.35 DOT PRODUCT (DOTPRXX)

##### Format

DOTPRXX(VA,INCA,VB,INCB,VC,NN,\*)

Ident (R:I) : 035:177517B

##### Explanation

Add the product of the corresponding elements of two vectors. This function corresponds to the mathematical dot product, also called scalar product, of two vectors.

$VC = VA_1 * VB_1 + VA_2 * VB_2 + \dots + VA_{nn} * VB_{nn}$ , 'nn' is the element count.

##### Parameters

VA : Name of input vector VA.  
INCA : VA index increment.  
VB : Name of input vector VB.  
INCB : VB index increment.  
VC : Name of output scalar VC.  
NN : Element count.

##### Listing

```
SUBROUTINE DOTPRXX(VA,INCA,VB,INCB,VC,NN,*)
DIMENSION VA(1),VB(1)
IA = 1
IB = 1
SUM = 0.0
DO FOR M = 1,NN
  SUM = SUM + VA(IA) * VB(IB)
  IA = IA + INCA
  IB = IB + INCB
ENDDO
VC=SUM
RETURN 1
END
```

#### 4.36 VECTOR CLEAR (VCLRXXX)

##### Format

VCLRXXX(VC,INCC,NN,\*)

Ident (R:I) : 036:177517B

##### Explanation

Set the elements of a vector to all zeros.

##### Parameters

VC : Name of output vector VC.  
INCC : VC index increment.  
NN : Element count.

##### Listing

```
SUBROUTINE VCLRXXX(VC,INCC,NN,*)  
DIMENSION VC(1)  
IC = 1  
DO FOR M = 1,NN  
    VC(IC) = 0.0  
    IC = IC + INCC  
ENDDO  
RETURN 1  
END
```



Performance

The execution time for the function depends on the element counts of NB and NC. Approximate execution time formulas (ftime) for the function are as follows.

ND-560/1:

ftime [microsec.] =  $NC * (1.35 * (NB-2) + 5.7)$  ,  $NB \leq 1000$ .

ftime [microsec.] =  $NC * (2.30 * NB + 4.0)$  ,  $NB > 1000$ .

ND-570/2:

ftime [microsec.] =  $NC * (0.88 * (NB-2) + 3.0)$  ,  $NB \leq 1000$ .

ftime [microsec.] =  $NC * (1.26 * NB + 2.0)$  ,  $NB > 1000$ .

#### 4.38 COMPLEX VECTOR MULTIPLY (CVMULXX)

##### Format

CVMULXX(VA,INCA,VB,INCB,VC,INCC,NN,NF,\*)      Ident (R:I) : 040:177517B

##### Explanation

Multiply two complex vectors. This function corresponds to mathematical multiplication of complex numbers. An own flag selects whether the result should be conjugated or not.  $VA = VAr + VAI$ ,  $VB = VBr + VBi$ .

If the conjugate flag  $\geq 0$  then:

$VC = (VAr * VBr - VAI*VBi)r + (VAr*VBi + VAI*VBr)i$ , else:

$VC = (VAr * VBr - VAI*VBi)r - (VAr*VBi + VAI*VBr)i$ .

'r' and 'i' denotes real and imaginary elements.

##### Parameters

VA      : Name of input vector VA.  
INCA    : VA index increment.  
VB      : Name of input vector VB.  
INCB    : VB index increment.  
VC      : Name of output vector VC.  
INCC    : VC index increment.  
NN      : Element count.  
NF      : Conjugate flag.

NF = +1 : Normal complex multiply.

NF = -1 : Multiply with conjugate of VA.

##### Listing

```
SUBROUTINE CVMULXX(VA,INCA,VB,INCB,VC,INCC,NN,NF,*)
DIMENSION VA(1),VB(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR M = 1,NN
  VC(IC) = VA(IA)*VB(IB)-VA(IA+1)*VB(IB+1)*NF
  VC(IC+1) = VA(IA)*VB(IB+1)+VA(IA+1)*VB(IB)*NF
  IA = IA + INCA
  IB = IB + INCB
  IC = IC + INCC
ENDDO
RETURN 1
END
```

**4.39 COMPLEX FAST FOURIER TRANSFORM (CFFTXXX)****Format**

```
CFFTXXX(C,N,LF,*)          Ident (R:I) : 054:177517B
                             Ident (R:I) : 055:177517B
                             Ident (R:I) : 056:177517B
                             Ident (R:I) : 057:177517B
                             Ident (R:I) : xxx:177516B
```

**Parameters**

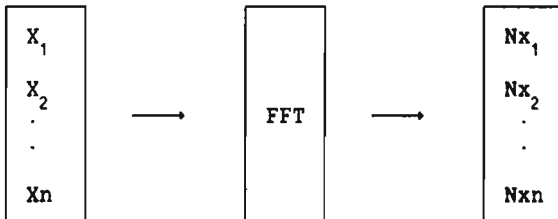
C : Name of complex input and output vector VC.  
 N : Complex element count, in power of 2.  
 LF : Direction flag.

LF = +1 : Forward FFT of vector VC.  
 LF = -1 : Reverse FFT of vector VC.

**Explanation**

To perform an in-place complex forward, or an inverse Fast Fourier Transform (FFT).

Symbolically the forward FFT can be represented by the block diagram:

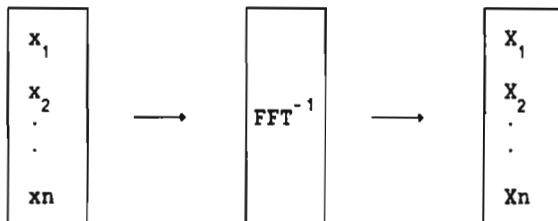


The 'X' denotes the complex input coefficients to the vector VC, and 'Nx' denotes the complex output coefficients in vector VC. 'n' is the element count.

NOTE The output coefficients should be multiplied with 1/N for properly scaling.



Symbolically the inverse FFT can be represented by the block diagram:



The 'x' denotes the complex input coefficients to the vector VC, and 'X' denotes the complex output coefficients in vector VC. 'n' is the element count. The output coefficients are properly scaled.

A series of radix 2 passes is used to obtain the coefficients.

A sine table is used to find sine and cosine, instead of calculating them. In this way, the routine is improved with respect to execution time. This is done for element count up to 65536 ( $2^{16}$ ). The sine table covers angles from 0 to  $\pi/2$ .

Listing

```

SUBROUTINE CFFTXXX(C,N,LF,*)
DIMENSION M(20)
COMPLEX C(N)
COMPLEX WK,HOLD,Q,CFN
FN = FLOAT(N)
F = FLOAT(LF)
X = ALOG2(FN)
N2 = NINT(X)

C                               MAX ELEMENT COUNT CFFT.
IF (N2 .GT. 20) STOP
DO 10 I = 1,N2
10  M(I) = 2**(N2-I)
FPX = F * 6.283185308 / FN
DO 40 L = 1,N2
  NBLOCK = 2**(L-1)
  LBLOCK = N / NBLOCK
  LBHALF = LBLOCK / 2
  K = 0
  DO 40 IBLOCK = 1,NBLOCK
    FK = K
    V = FPX * FK
    COSV = COS(V)
    SINV = SIN(V)
    WK = CMPLX (COSV,SINV)
    ISTART = LBLOCK * (IBLOCK-1)
    DO 20 I = 1,LBHALF
      J = ISTART + I
      JH = J + LBHALF
      Q = C(JH) * WK
      C(JH) = C(J) - Q
      C(J) = C(J) + Q
20  CONTINUE
    DO 30 I = 2,N2
      II = I
      IF (K .LT. M(I)) GO TO 40
30  K = K - M(I)
40  K = K + M(II)

```

```

C      REORDERING THE TRANSFORM:

      K = 0
      DO 70 J = 1,N
        IF (K .LT. J) GO TO 50
        HOLD = C(J)
        C(J) = C(K+1)
        C(K+1) = HOLD
50     DO 60 I = 1,N2
        II = I
        IF (K .LT. M(I)) GO TO 70
60     K = K - M(I)
70     K = K + M(II)
      IF (F .LT. 0.0) RETURN 1
C      INVERSE TRANSFORM

      CFN = CMLPX (FN,0.0)
      DO 80 I = 1,N
80     C(I) = C(I) / CFN
      RETURN 1
      END
  
```

Performance

This table for CFFT function provides version C or newer of the APF library.

Number of elements	Improvement ratio to FORTRAN		Typical execution time pr. loop (millisec.)	
	ND-560/1	ND-570/2	ND-560/1	ND-570/2
32	4.35	3.66	1.26	0.83
64	4.25	3.57	2.80	1.84
128	4.15	3.55	6.10	4.00
256	4.00	3.50	13.55	8.77
512	3.95	3.38	29.25	19.25
1024	3.80	3.30	63.75	41.88
2048	3.75	2.80	138.00	91.00
4096	3.65	2.73	297.50	240.00
8192	3.55	2.70	640.00	520.00
16384	3.35	2.70	1460.00	1100.00
32768	3.30	2.68	3140.00	2360.00
65536	3.25	2.68	6700.00	4960.00

References

Among many references on FFT are :

- G. D. Bergland: "A Guided Tour of the Fast Fourier Transform"  
IEEE Spectrum, July 1969.
- E. O. Brigham: "The Fast Fourier Transform"  
Prentice-Hall, Englewood Cliffs, 1974.

#### 4.40 REAL FAST FOURIER TRANSFORM (RFFTXXX)

##### Format

RFFTXXX(C,N,LF,\*)

Ident (R:I) : 061:177517B

Ident (R:I) : 062:177517B

##### Parameters

C : Name of complex input and output vector VC.

N : Complex element count, in power of 2.

LF : Direction flag.

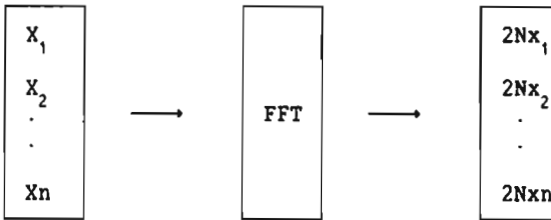
LF = +1 : Forward FFT of vector VC.

LF = -1 : Reverse FFT of vector VC.

##### Explanation

To perform an in-place real to complex forward, or complex to real inverse Fast Fourier Transform (FFT).

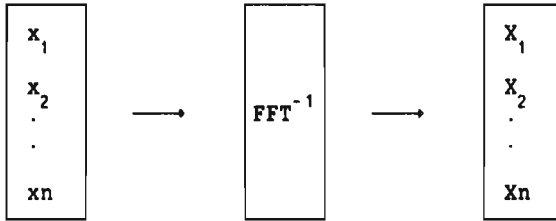
Symbolically the forward FFT can be represented by the block diagram:



The 'X' denotes the real input coefficients to the vector VC, and '2Nx' denotes the complex output coefficients in vector VC. 'n' is the element count.

NOTE The output coefficients should be multiplied with 1/2N for properly scaling.

Symbolically the inverse FFT can be represented by the block diagram:



The 'x' denotes the complex input coefficients to the vector VC, and 'X' denotes the real output coefficients in vector VC. 'n' is the complex element count. The output coefficients are properly scaled.

The RFFTXXX routine utilizes the CFFTXXX routine, refer to section 4.39.

Listing

```

SUBROUTINE RFFTXXX(C,N,LF,*)
COMPLEX C(1)
COMPLEX UC,VC,UC2,VC2,WK,WK2,CFN
F      = FLOAT(LF)
NHALF = N / 2
NFOUR = N / 4
VK      = F*3.141592654 / NHALF
C
Using the original CFFT routine.
      CFFTXXX(C,NHALF,LF,*910)
910 CONTINUE

IF (F .LT. 0.0) THEN
  FDIV1 = 1.0
  FDIV2 = 2.0
ELSE
  FDIV1 = 2.0
  FDIV2 = 4.0
ENDIF
URE = REAL(C(1))
VRE = AIMAG(C(1))
CRE = (URE+VRE) / FDIV1
CIM = (URE-VRE) / FDIV1
C(1) = CMPLX (CRE,CIM)
URE = (REAL(C(NFOUR+1))) / FDIV1
VRE = (F*AIMAG(C(NFOUR+1))) / FDIV1
C(NFOUR+1) = CMPLX (URE,VRE)
IRX = NHALF + 2
DO 200 IR = 2 , NFOUR
  IR2 = IR - IR
  FIR = IR - 1
  URE = (REAL(C(IR)) + REAL(C(IR2))) / FDIV2
  UIM = (AIMAG(C(IR)) - AIMAG(C(IR2))) / FDIV2
  VRE = (AIMAG(C(IR)) + AIMAG(C(IR2))) / FDIV2
  VIM = (REAL(C(IR2)) - REAL(C(IR))) / FDIV2
  UC = CMPLX (URE,UIM)
  VC = CMPLX (VRE,VIM)
  UC2 = CONJG (UC)
  VC2 = CONJG (VC)
  V = VK * FIR
  COSV = COS(V)
  SINV = SIN(V)
  WK = CMPLX (COSV,SINV)
  WK2 = CMPLX (-COSV,SINV)
  C(IR) = UC + VC * WK
  C(IR2) = UC2 + VC2 * WK2
200 CONTINUE
RETURN 1
END

```

Performance

This table for RFFT function provides version C or newer of the APF library.

Number of elements	Improvement ratio to FORTRAN		Typical execution time pr. loop (millisec.)	
	ND-560/1	ND-570/2	ND-560/1	ND-570/2
32	2.20	2.10	1.40	0.82
64	2.20	2.10	3.00	1.77
128	2.25	2.10	6.30	3.76
256	2.30	2.10	13.20	8.05
512	2.30	2.10	27.80	17.00
1024	2.30	2.15	58.00	35.80
2048	2.30	2.15	121.00	74.50
4096	2.30	2.15	252.50	156.25
8192	2.30	2.05	530.00	375.00
16384	2.35	2.05	1090.00	780.00
32768	2.30	2.05	2360.00	1640.00
65536	2.30	2.05	4940.00	3420.00

For references on FFT, see page 60.



#### 4.41 VECTOR TAPER (VTAPERX)

##### Format

VTAPERX(VA,VC,NN,IFLAG,\*)

Ident (R:I) : 041:177517B

##### Explanation

Multiply each element of a vector with an increasing or decreasing factor. An own flag selects either the decreasing or the increasing factor. The factor is a function of the element count.

If flag > 0 then:

$$VC_1 = VA_1 * (1/nn), VC_2 = VA_2 * (2/nn) \dots VC_{nn} = VAn * (1).$$

So the general element equation is:  $VC_n = VAn * (n/nn)$ .

If flag  $\leq$  0 then:

$$VC_1 = VA_1 * (1 - 1/nn), VC_2 = VA_2 * (1 - 2/nn) \dots VC_{nn} = VAn * (0).$$

So the general element equation is:  $VC_n = VAn * (1 - n/nn)$ .

'nn' denotes the element count and 'n' the element index.

##### Parameters

VA : Name of input vector VA.  
VC : Name of output vector VC.  
NN : Element count.  
IFLAG : Flag.

##### Listing

```
      SUBROUTINE VTAPERX(VA,VC,NN,IFLAG,*)
      DIMENSION VA(1),VC(1)
      REAL MULT,MINC
      IF (IFLAG .LE. 0) GO TO 10
      MULT = 1.0/NN
      MINC = MULT
      GO TO 20
10     CONTINUE
      MULT = (NN-1)*1.0/NN
      MINC = -1.0/NN
20     CONTINUE
      DO 30 I = 1,NN
         VC(I) = VA(I) * MULT
         MULT = MULT + MINC
30     CONTINUE
      RETURN 1
      END
```



```
DO 100 J = 2,L2
  K = L - J + 1
  HOLD = A(J)
  A(J) = A(J) + AL * A(K)
  D = D + A(J) * R(K+1)
  A(K) = A(K) + AL * HOLD
100  D = D + A(K) * R(J+1)
150  IF (2*L2 .EQ. L) GO TO 200
  LH = L2 + 1
  A(LH) = A(LH) + AL * A(LH)
  D = D + A(LH) * R(LH+1)
200  IF (ISW .EQ. 0) GO TO 600
  F(L) = (G(L) - Q)/V
  FL = F(L)
  L1 = L - 1
  Q = FL * R(2)
DO 300 J = 1,L1
  K = L - J + 1
  F(J) = F(J) + FL * A(K)
300  Q = Q + F(J) * R(K+1)
600  CONTINUE
  RETURN 1
  END
```

#### 4.43 VECTOR GENERATE (VGENXXX)

##### Format

VGENXXX(SCALAR, SCINC, VC, INCC, NN, \*)                      Ident (R:I) : 043:177517B

##### Explanation

Form a vector as a ramp function with a start value and a slope as input parameters.

$$VC_1 = sc + scinc, VC_2 = sc + 2 * scinc .. VC_{nn} = sc + nn * scinc.$$

So the general element expression is:  $VC_n = sc + n * scinc.$

'nn' denotes the element count, 'n' the element index, 'sc' start value, and 'scinc' slope.

##### Parameters

SCALAR : Scalar for start value.  
 SCINC : Scalar for increment.  
 VC : Name of output vector VC.  
 INCC : VC index increment.  
 NN : Element count.

##### Listing

```

SUBROUTINE VGENXXX(SCALAR, SCINC, VC, INCC, NN, *)
  DIMENSION V(1)
  IC = 1
  SC = 0.0
  DO FOR I = 1, NN
    VC(IC) = SCALAR + SC
    IC = IC + INCC
    SC = I * SCINC
  ENDDO
  RETURN 1
END

```

#### 4.44 VECTOR LINEAR INTERPOLATION (VNMOXXX)

##### Format

VNMOXXX(VA,VB,VR,LA,LB,\*)

Ident (R:I) : 044:177517B

##### Explanation

Perform linear interpolation between samples.

##### Parameters

VA : Name of input vector VA.  
VB : Name of input vector VB.  
VR : Name of output vector VR.  
LA : Element count vector VA.  
LB : Element count vector VB.

##### Listing

```
      SUBROUTINE VNMOXXX(VA,VB,VR,LA,LB,*)
      DIMENSION VA(1),VB(1),VR(1)
      IFLAG = 0
      LA1 = LA + 1
      DO 20 M = 1, LB
          IF (VB(M) .GT. 0.0) GO TO 21
20      VR(M) = 0.0
21      CONTINUE
          IF (M .GT. 1) GO TO 40
      DO 30 M = 1, LB
          IF ((VB(M+1)-VB(M)) .NE. 0.0) GO TO 40
30      VR(M) = 0.0
40      CONTINUE
      L = M
      DO 100 M = L, LB
          IF(VB(M).GT.LA1)THEN
              VR(M) = 0.0
              GO TO 100
          ENDIF
          IF (IFLAG .EQ. 1) GO TO 70
          IF (M .EQ. LB) GO TO 70
          IF (VB(M+1) .LT. VB(M)) THEN
      DO 60 I = 1, M
60      VR(I) = 0.0
          IFLAG = 1
          GO TO 100
      ENDIF
```

70

ND-500 SINGLE PRECISION ARRAY PROCESSING FUNCTIONS  
ARRAY PROCESSING FUNCTIONS

70

```
CONTINUE
IB = INT(VB(M))
FB = VB(M) - IB
IF (IB .LE. 0) THEN
  VR(M) = 0.0
ELSE
  VR(M) = (VA(IB+1) - VA(IB))*FB + VA(IB)
ENDIF
```

100

```
CONTINUE
RETURN 1
END
```

#### 4.45 VECTOR SINC INTERPOLATION (VNMOSXX)

##### Format

VNMOSXX(VA,VB,VR,LA,LB,\*)

Ident (R:I) : 045:177517B

##### Explanation

Perform sinc interpolation between samples.

##### Parameters

VA : Name of input vector VA.  
VB : Name of input vector VB.  
VR : Name of vector VR.  
LA : Element count vector VA.  
LB : Element count vector VB.

##### Listing

```
      SUBROUTINE VNMOSXX(VA,VB,VR,LA,LB,*)
      DIMENSION VA(1),VB(1),VR(1)
      DIMENSION FILTER(8,7)
      DATA FILTER/
C
      + -0.00442400 , 0.02585229 , -0.08848375 , 0.97214937 ,
      + 0.12341321 , -0.03566697 , 0.00774525 , -0.00007569 ,
C
      + -0.00583580 , 0.0402596 , -0.14005053 , 0.89166689 ,
      + 0.27481657 , -0.07685405 , 0.01818759 , -0.00057665 ,
C
      + -0.00514438 , 0.04393956 , -0.15734833 , 0.76733017 ,
      + 0.44274765 , -0.11675274 , 0.02960985 , -0.00174663 ,
C
      + -0.00346141 , 0.03929961 , -0.14670730 , 0.61239052 ,
      + 0.61239052 , -0.14670724 , 0.03929964 , -0.00346142 ,
C
      + -0.001746630, 0.02960985 , -0.11675292 , 0.44274879 ,
      + 0.76732922 , -0.15734845 , 0.04393965 , -0.00514441 ,
C
      + -0.00057664 , 0.01818759 , -0.07685423 , 0.27481735 ,
      + 0.89166594 , -0.14005071 , 0.04025969 , -0.00583582 ,
C
      + -0.00007568 , 0.00774526 , -0.03566715 , 0.12341386 ,
      + 0.97214890 , -0.08848411 , 0.02585241 , -0.00442402 /

      DATA NFPTS /8/

      IFLAG = 0
      LA1 = LA + 1
      DO 20 M = 1, LB
```

```

    IF (VB(M) .GT. 0.0) GO TO 21
20   VR(M) = 0.0
21   CONTINUE
    IF (M .GT. 1) GO TO 40
    DO 30 M = 1, LB
        IF ((VB(M+1)-VB(M)) .NE. 0.0) GO TO 40
30   VR(M) = 0.0
40   CONTINUE
    L = M
    DO 100 M = L, LB
        IF (VB(M) .GT. LA1) THEN
            VR(M) = 0.0
            GO TO 100
        ENDIF
        IF (IFLAG .EQ. 1) GO TO 70
        IF (M .EQ. LB) GO TO 70
        IF (VB(M+1) .LT. VB(M)) THEN
60   DO 60 I = 1, M
            VR(I) = 0.0
            IFLAG = 1
            GO TO 100
        ENDIF
70   CONTINUE
        IB = INT(VB(M))
        FB = VB(M) - IB
        IF ((IB-3) .GT. 0 .AND. (IB+4) .LE. LA) THEN
            NRFILT = .5 + FB / .125
            GO TO (1, 2, 2, 2, 2, 2, 2, 2, 3), NRFILT+1
1   VR(M) = VA(IB)
            GO TO 4
3   VR(M) = VA(IB+1)
            GO TO 4
2   VR(M) = FDOTPR(VA(IB-3), FILTER(1, NRFILT), NFPTS)
4   CONTINUE
        ELSEIF (IB .LE. 0) THEN
            VR(M) = 0.0
        ELSEIF (M .EQ. LB) THEN
            VR(M) = VA(IB)
        ELSE
            VR(M) = (VA(IB+1) - VA(IB))*FB + VA(IB)
        ENDIF
100  CONTINUE
    RETURN 1
END
FUNCTION FDOTPR(VA, VB, N)
DIMENSION VA(1), VB(1)
FDOTPR = 0.0
DO FOR I = 1, N
    FDOTPR = FDOTPR + VA(I)*VB(I)
ENDDO
RETURN
END

```



**4.46 VECTOR EXPAND (VXPNDXX)**

Format

VXPNDXX(VA,VC,NN,NC,\*)

Ident (R:I) : 052:177517B

Explanation

Expand input vector VA into output vector VC.

Vector VA must be organized in this way:

VA<sub>1</sub>, VA<sub>2</sub>, VA<sub>3</sub>, ..., VA<sub>nn-1</sub> contain the arguments for the function in increasing order. VA<sub>2</sub>, VA<sub>3</sub>, ..., VA<sub>nn-1</sub> contain the corresponding function values. The argument in VA<sub>1</sub> must be greater or equal to 1.0.

This is also expressed as:  $VA_{2i} = f(VA_{2i-1})$ , for  $i \leq nn/2$ .

'nn' denotes the element count.

After execution, VC contains the new function values approximated for the arguments 1,2,3,4, ..., VC<sub>nn-1</sub>. The approximation method is based on linear interpolation. Remember that VC must be large enough to contain the number of elements specified by VC<sub>nn-1</sub>.

Parameters

- VA : Name of input vector.
- VC : Name of result vector.
- NN : Element count in input vector.
- NC : Element count in result vector.

Listing

```

SUBROUTINE VXPNDXX(VA,VC,NN,NC,*)
  DIMENSION VA(1),VC(1)
  IFIRST = 1
  LOOP = NN - 3
  DO 100 I = 1,LOOP,2
    SLOPE = (VA(I+3)-VA(I+1))/(VA(I+2)-VA(I))
    ILAST = VA(I+2)
    RINC = SLOPE*(IFIRST-VA(I))
    DO 50 J = IFIRST,ILAST
      VC(J) = VA(I+1)+RINC
      RINC = RINC+SLOPE
50    CONTINUE
    IFIRST = ILAST+1
100  CONTINUE
    NC = VA(NN-1)
    RETURN 1
  END
  
```

**4.47 VECTOR FIRST AND LAST NON-ZERO VALUE (VFLNZXX)****Format**

VFLNZXX(VA,XINDF,XINDL,NN,\*)

Ident (R:I) : 051:177517B

**Explanation**

Find the indices of the first and last non-zero elements in a vector.

**Parameters**

VA : Name of input vector VA.  
 XINDF : Name for first non-zero index.  
 XINDL : Name for last non-zero index.  
 NN : Element count.

**Listing**

```

SUBROUTINE VFLNZXX(VA,XINDF,XINDL,NN,*)
DIMENSION VA(1)
DO 100 I = 1,NN
  IF (VA(I) .NE. 0.0) THEN
    XINDF = I
    GO TO 105
  ENDIF
100 CONTINUE
XINDF = NN
XINDL = 1
GO TO 205
105 CONTINUE
DO 200 I = NN,1,-1
  IF (VA(I) .NE. 0.0) THEN
    XINDL = I
    GO TO 205
  ENDIF
200 CONTINUE
205 RETURN 1
END

```

#### 4.48 VECTOR SCALAR MULTIPLY AND ADD (VSMADDX)

##### Format

VSMADDX(VA,INCA,SC,VB,INCB,VC,INCC,NN,\*)      Ident (R:I) : 053:177517B

##### Explanation

Add the corresponding elements from two vectors, where the elements of one of the vectors are multiplied with a scalar value.

$VC_n = VA_n * sc + VB_n$ , where 'sc' denotes the scalar, and 'n' denotes the element index.

##### Parameters

VA        : Name of input vector VA.  
INCA     : VA index increment.  
SC        : Scalar value.  
VB        : Name of input vector VB.  
INCB     : VB index increment.  
VC        : Name of output vector VC.  
INCC     : VC index increment.  
NN        : Element count.

##### Listing

```
SUBROUTINE VSMADDX(VA,INCA,SC,VB,INCB,VC,INCC,NN,*)
DIMENSION VA(1),VB,(1),VC(1)
IA = 1
IB = 1
IC = 1
DO FOR I = 1,NN
  VC(IC)= VA(IA) * SC + VB(IB)
  IA   = IA + INCA
  IB   = IB + INCB
  IC   = IC + INCC
ENDDO
RETURN 1
END
```

**4.49 PREDICT (PREDICT)****Format**

PREDICT(VA,VB,N,L,\*)

Ident (R:I) : 046:177517B

**Explanation**

Form the vector VB with  $VB_1$  equal to 1.0, the next elements  $VB_2, VB_3, \dots, VB_L$  equal to 0.0, and the elements  $VB_{L+1}, VB_{L+2}, \dots, VB_{L+N}$  elements equal to  $-VA_1, -VA_2, \dots, -VA_N$ .

Note that the elements in VA also are multiplied with -1.

**Parameters**

VA : Name of input vector VA.  
 VB : Name of output vector VB.  
 N : Element count for number of negative elements.  
 L : Element count for number of zero elements.  
 Element count of VB must be at least :  $N + L$ .

**Listing**

```

SUBROUTINE PREDICT(VA,VB,N,L,*)
DIMENSION VA(1),VB(1)
DO 100 I = 1,L
  VA(I) = (-1.0)*VA(I)
  VB(1) = 1.0
DO 200 I = 2,N
  VB(I) = 0.0
DO 300 I = 1,L
  VB(I+N) = VA(I)
RETURN 1
END

```

**4.50 DISPLAY PROCESSOR FUNCTION (XBTMUX)**

Format

XBTMUX(IBSWTH,ISCANS,NDOTS,\*)

Ident (R:I) : 001:177507B

Explanation

Put on proper raster bits for 32 scan lines for a display processor. A swath is converted to a scan.

Parameters

IBSWTH : Name of input vector IBSWTH.  
 ISCANS : Name of output vector ISCANS.  
 NDOTS : Element count.

Listing

```

SUBROUTINE XBTMUX (IBSWTH,ISCANS,NDOTS,*)
  INTEGER*4 IBSWTH(1)
  INTEGER*4 ISCANS(1)
  INTEGER*4 NDOTS
  INTEGER*4 IMASK(32)
  DATA IMASK/

- 20000000000B,10000000000B,04000000000B,02000000000B,
- 01000000000B,00400000000B,00200000000B,00100000000B,
- 00040000000B,00020000000B,00010000000B,00004000000B,
- 00002000000B,00001000000B,00000400000B,00000200000B,
- 00000100000B,00000040000B,00000020000B,00000010000B,
- 00000004000B,00000002000B,00000001000B,00000000400B,
- 00000000200B,00000000100B,00000000040B,00000000020B,
- 00000000010B,00000000004B,00000000002B,00000000001B/

  ISCAN = 1
  IND = 1
10  CONTINUE
  MASK = IMASK(ISCAN)
  NBIT = 1
  ISWD = 0
  DO 100 N=1,NDOTS
    IBIT = IAND(IBSWTH(N),MASK)
    IF (IBIT.NE.0) ISWD=IOR(ISWD,IMASK(NBIT))
    NBIT = NBIT + 1
    IF (NBIT.LE.32) GOTO 100
    ISCANS(IND) = ISWD
    IND = IND + 1
    NBIT = 1
    ISWD = 0
100 CONTINUE
  ISCAN = ISCAN + 1
  IF (ISCAN.LE.32) GOTO 10
  RETURN 1
END

```

**4.51 IMAGE BUILD (IMGBLD)**Format

IMGBLD(IBPOS,IBSET,NN,ISWTH,\*)

Ident (R:I) : 002:177507B

Explanation

Raster 32 scans input.

Parameters

IBPOS : Name of input/output vector IBPOS.  
 IBSET : Name of input/output vector IBSET.  
 NN : Element count.  
 ISWTH : Name of output vector ISWTH.

Listing

```

SUBROUTINE IMGBLD(IBPOS,IBSET,NN,ISWTH,*)
  INTEGER*4 IBPOS(1)
  INTEGER*4 IBSET(1)
  INTEGER*4 NWDS
  INTEGER*4 ISWTH(1)
  INTEGER*4 IBIT(33)
  DATA IBIT/
- 000000000000B,
- 200000000000B,300000000000B,340000000000B,360000000000B,
- 370000000000B,374000000000B,376000000000B,377000000000B,
- 377400000000B,377600000000B,377700000000B,377740000000B,
- 377760000000B,377770000000B,377774000000B,377776000000B,
- 377777000000B,377777400000B,377777600000B,377777700000B,
- 377777740000B,377777760000B,377777770000B,377777774000B,
- 377777776000B,377777777000B,377777777400B,377777777600B,
- 377777777700B,377777777740B,377777777760B,377777777770B,
  377777777774B,377777777776B,377777777777B/

  DO 100 N=1,NN
    NBITS = IBSET(N)
    IF (NBITS.LE.0) GOTO 100
    NBEG = IBPOS(N)
    IF (NBEG.LT.32) GOTO 50
    IBPOS(N) = NBEG - 32
  GOTO 100
50  CONTINUE
    NEND = NBEG+NBITS
    NSET = NBITS
    IF (NEND.LE.32) GOTO 60
    NSET = 32 - NBEG
    NEND = 32
  
```

```
60  CONTINUE
     NP = NBEG + 1
     NS = NEND+1
     IPAT = Ieor(ibit(np), ibit(ns))
     ISWTH(N) = Ior(ipat, iswth(N))
     IBSET(N) = NBITS-NSET
     IBPOS(N) = 0
100 CONTINUE
     RETURN 1
     END
```

#### 4.52 CONVERT AND MOVE (APMOVE)

##### Format

```
APMOVE(ADDR1,ADDR2,IFTM,NN,*)          Ident (R:I) : 060:177517B
```

##### Explanation

Convert input vector (pointed to by ADDR1) according to the format descriptor IFTM, and move the result to output vector (pointed to by ADDR2).

To get the pointer to a vector, the routine LOCARG must be called. It has the call format:

```
ADDR = LOCARG(V) ,
```

which means integer ADDR points at vector V after execution of the call. See also page 5, and the listing in the end of this section.

Format conversion:

```
IFTM = 0: Integer*4 (32 bits) into single floating point.
IFTM = 1: Integer*2 (16 bits) into single floating point.
IFTM = 2: 32 bits move operation.
IFTM = 3: Single floating point into integer*4 (32 bits).
IFTM = 4: Single floating point into integer*2 (16 bits).
IFTM ≥ 5: 32 bits move operation.
```

##### Parameters

```
ADDR1 : Pointer to address of input vector.
ADDR2 : Pointer to address of output vector.
IFTM   : Format descriptor.
NN     : Element count.
```

##### Listing

```
ROUTINE  APMOVE
DSTK: STACK FIXED
APAR1: W BLOCK 1
APAR2: W BLOCK 1
APAR3: W BLOCK 1
APAR4: W BLOCK 1
COUNT: W BLOCK 1
ENDSTACK

APMOVE: ENTF DSTK
W1 := IND(B.APAR1)   %.. Get input address.
W2 := IND(B.APAR2)   %.. Get output address.
W4 := IND(B.APAR4)   %.. Get element count.
W3 := IND(B.APAR3)   %.. Get format description.
IF -Z GO FMT1        %.. If IFTM = 0 : next.
```



```

%      Integer*4 to single float convert and move.
      W SET1 W3
LOOP0: W FCONV W1.0,W2.0; W1+4; W2+4; W LOOP1 W3,W4,LOOP0
      GO END

FMT1:  W DECR W3           %.. IFTM = IFTM - 1.
      IF -Z GO FMT2       %.. If IFTM = 0 : next.

%      Integer*2 to single float convert and move.
      W SET1 W3
LOOP1: H FCONV W1.0,W2.0; W1+2; W2+4; W LOOP1 W3,W4,LOOP1
      GO END

FMT2:  W DECR W3           %.. IFTM = IFTM - 1.
      IF -Z GO FMT3       %.. If IFTM = 0 : next.

%      Single float move .
FMT5:  W BMOVE W1.0,W2.0,W4
      GO END

FMT3:  W DECR W3           %.. IFTM = IFTM - 1.
      IF -Z GO FMT4       %.. If IFTM = 0 : next.

%      Single float to integer*4 convert and move.
      W SET1 W3
LOOP3: F WCONV W1.0,W2.0; W1+4; W2+4; W LOOP1 W3,W4,LOOP3
      GO END

FMT4:  W DECR W3           %.. IFTM = IFTM - 1.
      IF -Z GO FMT5       %.. If IFTM = 0 : next, else
                        %.. IFTM = 5 is assumed.

%      Single float to integer*2 convert and move.
      W SET1 W3
LOOP4: F HCONV W1.0,W2.0; W1+4; W2+2; W LOOP1 W3,W4,LOOP4
      GO END

END:   R := B.PREVB
      W MOVE 1,R.AUX
      RET
      ENDRoutine

      Routine LOCARG
DSTK:  STACK FIXED
INARG: W BLOCK 1
      ENDSTACK

LOCARG: ENTf DSTACK
      W1 := B.INARG
      RET
      ENDRoutine
  
```

#### 4.53 DEMULTIPLEX (DMXB)

##### Format

DMXB(INDAT,INGAIN,OUTPUT,IFIXGN,GNLOC,NBYSCN,NSAMP)

Ident (R:I) : xxx:177505B

Ident (R:I) : xxx:177506B

##### Explanation

Demultiplex of field tape.

##### Parameters

INDAT : Name of input vector.  
 INGAIN : Gain code buffer address.  
 OUTPUT : Name of output vector.  
 IFIXGN : Initial / early gain.  
 GNLOC : Gain location 4 bit index.  
 NBYSCN : Number of bytes in each scan.  
 NSAMP : Element count.

GNLOC is an odd number : High order 4 bit group byte.

GNLOC is an even number : Low order 4 bit group byte.

##### Listing

```

ROUTINE DMXB
PARMS:  STACK FIXED
INDAT:  W BLOCK 1
INGAIN: W BLOCK 1
OUTPUT: W BLOCK 1
IFIXGN: W BLOCK 1
GNLOC:  W BLOCK 1
NBYSCN: W BLOCK 1
NSAMP:  W BLOCK 1

%       Scaler for any given gain is 2**(GAIN*(-1)).

%       Note that the least significant bit is not used
%       and bit 1 corresponds to 0.5 millivolt.

GNTAB:  W DATA 07760000000B    % Scaler for gain = 0
        W DATA 07740000000B    % Scaler for gain = 1
        W DATA 07720000000B    % Scaler for gain = 2
        W DATA 07700000000B    % Scaler for gain = 3
        W DATA 07660000000B    % Scaler for gain = 4
        W DATA 07640000000B    % Scaler for gain = 5
        W DATA 07620000000B    % Scaler for gain = 6
        W DATA 07600000000B    % Scaler for gain = 7
        W DATA 07560000000B    % Scaler for gain = 8

```

```

W DATA 07540000000B    % Scaler for gain = 9
W DATA 07520000000B    % Scaler for gain = 10
W DATA 07500000000B    % Scaler for gain = 11
W DATA 07460000000B    % Scaler for gain = 12
W DATA 07440000000B    % Scaler for gain = 13
W DATA 07420000000B    % Scaler for gain = 14
W DATA 07400000000B    % Scaler for gain = 15
W DATA 07360000000B    % Scaler for gain = 16
W DATA 07340000000B    % Scaler for gain = 17
W DATA 07320000000B    % Scaler for gain = 18
W DATA 07300000000B    % Scaler for gain = 19
W DATA 07260000000B    % Scaler for gain = 20
W DATA 07240000000B    % Scaler for gain = 21
W DATA 07220000000B    % Scaler for gain = 22
W DATA 07200000000B    % Scaler for gain = 23
W DATA 07160000000B    % Scaler for gain = 24
W DATA 07140000000B    % Scaler for gain = 25
W DATA 07120000000B    % Scaler for gain = 26
W DATA 07100000000B    % Scaler for gain = 27
W DATA 07060000000B    % Scaler for gain = 28
W DATA 07040000000B    % Scaler for gain = 29
W DATA 07020000000B    % Scaler for gain = 30
W DATA 07000000000B    % Scaler for gain = 31

LIMIT:  W BLOCK 1
NUMSAM: W BLOCK 1
IGAIN:  W BLOCK 1
MASKI:  W BLOCK 1
        ENDSTACK
  
```

% Gain type 2 - SEG B compatible gain configuration.

```

DMXB:  ENTF PARM$
SEGB:  W2 := B.INGAIN    % Address of gain values.
        W3 := B.INDAT    % Address of input.
        R := B.OUTPUT    % Address of output.
        W1 := IND(B.NSAMP) % Element count.
        W1 :=: B.NUMSAM   % Save as loop counter.
        W SET1 B.LIMIT    % Set lower limit for loop.
        W1 := IND(B.IFIXGN) % Fixed gain.
        W1 LADDR B.GNTAB(W1) % Address of gain table.
        W1 :=: B.IGAIN    % 4 bit gain index.
        W4 := IND(B.GNLOC) % High or low order 4 bit.
        BI1 := BI4        % Adjust for 0 based indexing.
        W4 - 1            % Divide by 2 to get byte index.
        W SHL W4,-1       % Point to proper gain byte.
        W2 + W4           % Number of bytes in each scan.
        W4 := IND(B.NBYSCN)
        W1 COMP 1

        IF = GO LOOPH    % Odd : Gain is in high order 4 bits.
  
```

```

%      Gain is in low order 4 bits of gain byte.

LOOPL:  BY1 := W2.0           % Gain byte.
        BY1 AND 15           % With proper gain bits.
        H FCONV W3.0,F2      % Convert I2 to R4.
        W2 + W4 ; W3 + W4    % Next gain byte and input data.
        F MUL3 IND(B.IGAIN)(W1),F2,R.0
        W RLADDR R.4         % Next output position.
        W LOOPD B.NUMSAM,B.LIMIT,LOOPL ; RET

%      Gain is in high order 4 bits of gain byte.

LOOPH:  BY1 := W2.0           % Gain byte.
        BY SHL BY1,-4        % With proper gain bits.
        H FCONV W3.0,F2      % Convert I2 to R4.
        W2 + W4 ; W3 + W4    % Next gain byte and input data.
        F MUL3 IND(B.IGAIN)(W1),F2,R.0
        W RLADDR R.4         % Next output position.
        W LOOPD B.NUMSAM,B.LIMIT,LOOPH ; RET

ENDROUTINE

```

**5 FAST BYTE MOVE**

Please refer to the ND-500 Reference Manual, ND-05.009, for a description of the notation etc.

An instruction for fast move of data is implemented. The speed for this instruction depends on the size of the data cache system. The data cache system is either a 128 Kbyte data cache (dc = 4), a 64 Kbyte data cache (dc = 2), a 32 Kbyte data cache (dc = 1), or no data cache at all (dc = 0).

**Format :** BY SSMOV <source/r/BY>,<destination/w/BY>,<m/r/W>

Assembly notation	Name	Hex code	Octal code
BY SSMOV	byte move	0FE77H	177167B

**Operation :**

```

i -> 0
while i < m do
    S(i..i+dc*4) -> D(i..i+dc*4) ; i + dc*4 -> i
enddo
    
```

**Description :**

<m> bytes are moved from <source> to <destination> operand. The source and destination operands are pointers to the start of the data blocks. Overlap is not taken care of. Constants and registers are illegal as source or destination operands and will cause an illegal operand specifier (IOS) trap condition. The source and destination addresses and number of bytes also have to be a multiplum of dc\*4 (either 16, 8 or 4), else an IOS trap condition will occur.

**Trap conditions** : Illegal operand specifier, addressing traps.

**Termination conditions** : Data status bits are reset. K = 0.

**Example:**

Copy a number of bytes from one location to another on a system with 128 Kbyte data cache (dc = 4):

```
BY SSMOV IND(B.24B),R.0,B.30B
```

The move will only be done as long as the following is true :

```

contents of B.24B      : pppppppppx0B
contents of R register : pppppppppy0B
contents of B.30B     : pppppppppz0B
    
```

where "p" means any value, and the legal values for x, y and z are 0, 2, 4 and 6.

The speed of the instruction depends on the system configuration. The maximum speed of the instruction is obtained on a system containing 128 Kbyte data cache. The speed is approximately four times the speed of the instruction BMOVE. With dc=1, the instruction runs at approximately the same speed as the instruction BMOVE.

Microseconds per byte moved for the instruction BY SSMOV:

Number of bytes		ND-560/1			ND-570/2	
Octal	Decimal	Data cache system:			Data cache system:	
		dc = 4	dc = 2	dc = 1	dc = 2	dc = 1
100B	64	0.127	0.192	0.290	0.187	0.265
200B	128	0.096	0.160	0.258	0.140	0.210
400B	256	0.082	0.145	0.243	0.113	0.187
1000B	512	0.073	0.137	0.234	0.105	0.175
2000B	1024	0.069	0.132	0.230	0.095	0.166
4000B	2048	0.068	0.130	0.228	0.092	0.163
10000B	4096	0.067	0.130	0.228	0.090	0.162
20000B	8192	0.067	0.129	0.226	0.089	0.161
40000B	16384	0.066	0.129	0.225	0.089	0.160
100000B	32768	0.066	0.129	0.225	0.089	0.160

Index

APF library . . . . .	1.
APMOVE . . . . .	80.
array processing, definition . . . . .	1, 2.
basic concepts . . . . .	1.
CFFTXXX . . . . .	56.
complex vector, definition . . . . .	2.
complex vector multiply . . . . .	55.
convert and move . . . . .	80.
convolution . . . . .	53.
CONVXXX . . . . .	53.
CVMULXX . . . . .	55.
demultiplex . . . . .	82.
display processor function . . . . .	77.
DMXB . . . . .	82.
dot product . . . . .	51.
DOTPRXX . . . . .	51.
elements, definition . . . . .	2.
element count, definition . . . . .	2.
fast byte move . . . . .	85.
fast fourier transform, complex . . . . .	56.
real . . . . .	61.
floating point accuracy . . . . .	1.
format . . . . .	1.
hardware concepts . . . . .	1.
IBMFCV . . . . .	35.
IBM to ND floating point convert . . . . .	35.
image build . . . . .	78.
IMGBLD . . . . .	78.
increment, definition . . . . .	2.
installation of software . . . . .	1.
maximum and minimum magnitude element in vector . . . . .	47.
maximum and minimum value in vector . . . . .	46.
maximum magnitude element in vector . . . . .	44.
maximum value in vector . . . . .	42.
MAXMGVX . . . . .	44.
MAXMINX . . . . .	46.
MAXVXXX . . . . .	42.
memory management system . . . . .	1.
microprogram . . . . .	1.
minimum magnitude element in vector . . . . .	45.
minimum value in vector . . . . .	43.
MINMGX . . . . .	45.
MINVXXX . . . . .	43.
MXMNGX . . . . .	47.
NDFCV . . . . .	33.
ND to IBM floating point convert . . . . .	33.
parallel processing . . . . .	1.
parameters, specification . . . . .	2.
performance, ND-560/1 . . . . .	11.
ND-570/2 . . . . .	13.
PREDICT . . . . .	76.

RFFTXXX . . . . .	61.
sum of vector elements . . . . .	37.
sum of vector elements magnitude . . . . .	38.
sum of vector elements signed square . . . . .	40.
sum of vector elements square . . . . .	39.
SVEMGXX . . . . .	38.
SVESQXX . . . . .	39.
SVEXXXX . . . . .	37.
SVSXXXX . . . . .	40.
use of processing functions . . . . .	5.
VABSXXX . . . . .	26.
VADDXXX . . . . .	16.
VAVGABS . . . . .	41.
VCLRXXX . . . . .	52.
VCOSXXX . . . . .	29.
VDIVSXX . . . . .	50.
VDIVXXX . . . . .	19.
vector	
absolute value . . . . .	26.
add . . . . .	16.
average absolute value . . . . .	41.
clear . . . . .	52.
cosine . . . . .	29.
divide . . . . .	19.
expand . . . . .	73.
first and last non-zero value . . . . .	74.
generate . . . . .	68.
linear interpolation . . . . .	69.
maximum . . . . .	20.
maximum magnitude . . . . .	22.
minimum . . . . .	21.
minimum magnitude . . . . .	23.
move . . . . .	30.
multiply . . . . .	18.
negative . . . . .	32.
scalar add . . . . .	48.
scalar divide . . . . .	50.
scalar multiply . . . . .	49.
scalar multiply and add . . . . .	75.
signed square . . . . .	25.
sinc interpolation . . . . .	71.
sine . . . . .	28.
square . . . . .	24.
square root . . . . .	27.
subtract . . . . .	17.
swap . . . . .	31.
taper . . . . .	65.
vector,	
definition . . . . .	2.
name . . . . .	2.
VFLN2XX . . . . .	74.
VGENXXX . . . . .	68.
VMAXMGX . . . . .	22.
VMAXXXX . . . . .	20.



VMINMGX . . . . .	23.
VMINXXX . . . . .	21.
VMOVXXX . . . . .	30.
VMULXXX . . . . .	18.
VNEGXXX . . . . .	32.
VNMOSXX . . . . .	71.
VNMOXXX . . . . .	69.
VSADDXX . . . . .	48.
VSINXXX . . . . .	28.
VSMADDX . . . . .	75.
VSMULXX . . . . .	49.
VSQRTXX . . . . .	27.
VSQXXX . . . . .	24.
VSSQXXX . . . . .	25.
VSUBXXX . . . . .	17.
VSWAPXX . . . . .	31.
VTAPERX . . . . .	65.
VXPNDXX . . . . .	73.
WIENERX . . . . .	66.
wiener filter . . . . .	66.
XBTMUX . . . . .	77.





